

CONTENTS

PART I: PRINCIPLES AND METHODS OF FORCE MEASUREMENT

1 INTRODUCTION TO FORCE MEASUREMENT	3
1.1 Various Approaches to Force Transduction	3
1.2 Newton – Measurement Unit of Force	6
1.3 Mechanical Measurements of Forces & Tribology	8
1.4 Force Transducers Other than Electrical	10
1.5 Terminology: Sensors or Transducers?	13
1.6 Force Measurement Systems	16
REFERENCES	20
2 ELECTRICAL METHODS OF FORCE MEASUREMENT	23
2.1 Energetical Aspects in Force Transduction	24
2.2 Examples of Force Measurement in Thermal Processes	27
2.3 Typical Requirements for Force Transducers	29
2.4 Force Transducers (FTs) Classifications	30
2.4.1 First Attempts of Force Transducers Systematization	30
2.4.2 German FT Classifications	32
2.4.3 Dutch FT Classifications	34
2.4.4 English FT Classifications	35
2.5 Nonconventional Types of Force Transducers	37
2.5.1 Electrodynamic Force Transducers	37
2.5.2 Galvanomagnetic Force Transducers (Based on Hall Effect)	37
2.5.3 Acoustic Force Transducers (SAWs)	38
2.6 An Enlarged Classification of Force Transducers	40
REFERENCES	44
3 RESISTIVE FORCE TRANSDUCERS	49
3.1 Resistive Force Transducers Types	50
3.2 Potentiometers	52
3.3 Pretensioned Wires	53
3.4 Strain Gauges	54
3.5 Piezoresistive Sensors	56
3.5.1 Silicon Devices	57
3.5.2 Carbon Film Coatings and Carbon Nanotubes (CNTs)	59

3.6	Force Sensing Resistors (FSRs)	62
3.7	Force Sensing Resistive Networks	65
	REFERENCES	68
4	INDUCTIVE FORCE TRANSDUCERS	73
4.1	LVDT (Linear Variable Differential Transformer)	74
4.2	Variable Reluctance Transducers	78
4.3	Mutual Inductance Variation Force Transducers	79
4.4	Inductive Eddy Current Transducer	81
4.5	Biparametric Inductive Force Transducers	81
4.5.1	Biparametric LR	81
4.5.2	Biparametric LC	82
	REFERENCES	85
5	CAPACITIVE FORCE TRANSDUCERS	87
5.1	Capacitive Force Transducers Classification	87
5.2	Capacitive Force Transducers (CFTs) with Plates	88
5.2.1	CFT with Variable Thickness of the Dielectric Pad	88
5.2.2	CFT with Variable Distance between Plates	90
5.2.3	CFT with Plates Arranged under a Certain Angle	91
5.3	Multiple Plates Capacitive Force Transducers	92
5.4	Interdigitated and Matrix of Capacitive Sensors	94
5.4.1	CFT with Interdigitated Electrodes	94
5.4.2	CFT Using a Matrix of Capacitive Sensing Elements	96
5.5	Cylindrical Capacitive Force Transducers	97
5.6	Applications Based on Electrostatic Forces	100
5.6.1	Electrostatic Force Balances	100
5.6.2	Other Applications of Electrostatic Forces for the Measurement of Mechanical Quantities	102
5.7	Electronic Circuits for Capacitive Transducers	103
	REFERENCES	105
6	PIEZOELECTRIC FORCE TRANSDUCERS (PZFTs)	109
6.1	Piezoelectric Materials	110
6.1.1	Quartz Crystals	110
6.1.2	Sensors with Organic Polymers	111
6.1.3	Solid State Devices	113
6.2	Unidirectional Piezoelectric Force Transducers	114
6.3	Tridirectional Piezoelectric Force Transducers	117
6.4	Piezoelectric Bimorph as Force Transducer	120
6.5	Electronic Circuits for Piezo Force Transducers	123
6.6	Complex Applications with Piezoelectric Devices	125
	REFERENCES	126

7 ELECTROMAGNETIC FORCE TRANSDUCERS.....	131
7.1 Classification	131
7.2 Magnetoresistive Force Transducers	135
7.3 Force Measurements in Magnetic Field.....	138
7.3.1 Resistive Force Transducers in Magnetic Field.....	139
7.3.2 Capacitive Force Transducers in Magnetic Field	140
7.3.3 Pressure Transducers Based on Magnetic Higher-Order Harmonic Fields	141
7.4 Electromagnetic Weighing by Force Compensation	142
7.5 Electromagnetic Devices for Small Forces.....	144
7.5.1 Electromagnetic Probes for Micro- and Nano-force Measurements	144
7.5.2 Magnetic Flux Quantum as a Sub-pico-newton Weight.....	146
7.5.3 Casimir Forces and Levitation Pressures Measurement	148
REFERENCES	149
8 ELECTRODYNAMIC FORCE TRANSDUCERS	153
8.1 Electrodynamic Force Compensation Principle.....	155
8.2 Load Cells with Electrodynamic Feedback	156
8.3 Electrodynamic Force Compensation Balances.....	157
8.3.1 Hydrodynamic Gravimetric Balance	157
8.3.2 Electrodynamic Vacuum Microbalance.....	158
8.3.3 Electrodynamic Devices for Small Particles Experiments.....	159
8.4 Micromechanical Testers with Moving Coils.....	160
8.5 Multifunctional Transducers with Moving Coils.....	161
REFERENCES	163
9 MAGNETOELASTIC FORCE TRANSDUCERS.....	165
9.1 The Magnetostrictive Principle.....	166
9.2 Classification of Magnetoelastic FTs	168
9.3 Axial Magnetoelastic Force Transducers	170
9.3.1 Magnetostrictive Strips and Bars.....	170
9.3.2 Magnetostrictive Amorphous Wires	172
9.4 Frame-Shaped Magnetoelastic Force Transducers	173
9.5 Tubular Magnetoelastic Force Transducers.....	174
9.6 Circular Magnetoelastic Force Transducers	176
9.7 Block-Shaped Magnetoelastic Force Transducers.....	178
9.8 Magnetoelastic Shafts for Torque Transducers	180
9.9 Magnetoelastic FTs Electronic Circuitry.....	181
REFERENCES	183
10 GALVANOMAGNETIC FORCE TRANSDUCERS.....	185
10.1 Hall Effect and Its Applications	186
10.2 Force Transducers Based on the Hall Effect.....	189

10.2.1	Hall Effect in Geotechnical Engineering	189
10.2.2	Medical Applications with Hall Sensors	190
10.3	Hall Devices for Other Mechanical Quantities	191
10.3.1	Displacement and Position Measurements Using Hall Sensors	191
10.3.2	Weighing Based on Hall Devices	192
10.3.3	Pressure and Flow Measurements by Means of Hall Sensors	193
10.3.4	Shock Measurements Using Hall Devices	194
10.3.5	Penetration Velocity and Rotational Speed Measured with Hall Sensors	195
10.4	Galvanomagnetic FTs in Complex Measurement Chains	196
10.4.1	Combined Measurands in Galvanomagnetic Force Transducers	196
10.4.2	Triaxial Galvanomagnetic Force Transducers	198
10.5	Other Electromagnetic Principles in Force Measurement	199
	REFERENCES	200
11	VIBRATING-WIRE FORCE TRANSDUCERS	203
11.1	Vibrating Wire as Force Measurement Principle	203
11.2	VWFTs' Structures and Characteristics	206
11.3	Electronic Circuits for VWTs	209
11.3.1	Vibrating-Wire Excitation Methods	209
11.3.2	Measuring Circuits for Vibrating-Wire Transducers	211
11.3.3	Digital Weighing Based on Vibrating-Wire Transducers	211
11.3.4	Virtual Musical Instruments Investigated by Means of VWFTs	212
11.4	Different Types of Vibrating-Wire Transducers	213
11.5	VWTs' Applications for Other Physical Quantities	217
11.5.1	Viscometers and Densimeters	217
11.5.2	"Piezometers" (for Underground Water Pressure)	219
11.5.3	Tiltmeters / Inclinometers and Slope Indicators	220
11.6	VWTs' Progress and Their Extended Utilization	220
	REFERENCES	223
12	RESONATOR FORCE TRANSDUCERS	227
12.1	Resonator Principle in Force Measurement	228
12.2	Materials for Resonators and Their Q-Factors	230
12.2.1	Quartz Resonators for Force Transducers	231
12.2.2	Silicon Resonators for Force Transducers	232
12.3	Various Shapes of Resonators	235
12.3.1	Resonating Beams for Force Transducers	235
12.3.2	Resonating Diaphragms / Membranes for Force / Pressure Transducers	237
12.3.3	Resonating Tubes for Force Transducers	238

12.4	Single Beam (Micro)Resonators	238
12.5	Double Beam (Micro)Resonators	240
12.5.1	Classical Double-Ended Tuning Forks (DETFs)	240
12.5.2	Modern Solutions for DETF Resonators.....	242
12.6	Metallic Triple Beam Resonators (MTBRs).....	244
12.6.1	Force Transducers with MTBRs	244
12.6.2	Torque Transducers with MTBRs.....	246
	REFERENCES	247
13	ACOUSTIC FORCE TRANSDUCERS	251
13.1	Interdigital Transducers (IDTs)	252
13.2	Acoustic Emission and Waveguides.....	254
13.2.1	Acoustic Emission Applications	254
13.2.2	Acoustic Waveguides Applications	254
13.3	Ultrasound Force Transducers	256
13.3.1	Industrial Applications of Ultrasound Force Transducers	256
13.3.2	Ultrasound Force Transducers for Food and Pharmacology.....	259
13.3.3	Medical Applications of Ultrasound Force Transducers	260
13.4	Acoustic Radiation Force Transducers	261
13.4.1	Acoustic Radiation Force Transducers in Medicine	261
13.4.2	Acoustic Radiation Force Transducers in Metrology	262
13.5	Surface Acoustic Wave (SAW) Transducers.....	264
13.5.1	SAW Force Transducers.....	265
13.5.2	SAW Torque Transducers	266
13.5.3	SAW Pressure Transducers	267
13.5.4	SAW Fluidic Transducers.....	267
13.6	SAW Electronic Circuits	268
	REFERENCES	272
14	GYROSCOPIC FORCE TRANSDUCERS	275
14.1	The Gyroscopic Principle in Force Measurement	275
14.2	Conventional Gyroscopic Force Transducers.....	277
14.3	Types of Micro-Gyroscopic Force Transducers	279
14.3.1	Inertial Gyroscopes	279
14.3.2	Piezoelectric Gyroscopes.....	281
14.3.3	Resonator / Vibrating Gyroscopes	282
14.3.4	Acoustic (and SAW) Gyroscopes	284
14.3.5	Coriolis Force Transducers in Medical Applications.....	285
14.4	Optical Gyroscopes.....	286
14.4.1	Fiber Optic Gyroscopes (FOGs).....	286
14.4.2	Laser Gyroscopes.....	288
14.4.3	MOEMS (Micro-Opto-Electro-Mechanical System) Gyroscope.....	288
14.5	A Topical Review of Gyroscopes.....	288
	REFERENCES	290

15	FORCE BALANCE TECHNIQUES	293
15.1	Force Balance Principle Applied to Transducers.....	294
15.2	Electromagnetic Force Compensation (EMFC).....	297
15.3	Electrostatic Force Compensation	299
15.4	Optical Devices Based on Force Feedback.....	302
	REFERENCES	304
16	MIXED METHODS IN FORCE MEASUREMENTS.....	307
16.1	Force Transducers Using Advanced Electronics	308
16.2	Cantilever Beams for Various Force Transducers	310
16.3	CNTs for Measuring Mechanical Quantities	312
16.4	Combined Methods of Force Transduction	316
16.4.1	Force Transducers in Medical Instruments.....	316
16.4.2	EMAT (Electro-Magnetic Acoustic Transducer) and Lorentz Force.....	318
16.4.3	Multitransducer Equipment	320
16.4.4	Force Transducers Involving Optical Techniques	321
	REFERENCES	324
 PART II: FORCE TRANSDUCERS COMPONENTS		
17	THE FORCE MEASUREMENT CHAIN.....	331
17.1	Force Measurement Chain Components	331
17.2	Strain Gauge Sensing.....	334
17.3	Strain Gauges Signal Conditioning.....	337
17.4	Strain Gauges Signal Processing.....	340
17.5	Data Presentation for Force Transducers	343
	REFERENCES	345
18	WHEATSTONE BRIDGE – THE BASIC CIRCUIT FOR STRAIN GAUGE FORCE TRANSDUCERS	347
18.1	Wheatstone Bridge – General Presentation.....	347
18.2	Wheatstone Bridge – Fundamental Properties	348
18.3	Bridge Compensation and Adjusting Resistors.....	350
18.4	Supply Possibilities for Wheatstone Bridges	352
18.5	Different Applications with Measuring Bridges	353
18.6	Further Connections for Wheatstone Bridges	356
	REFERENCES	358
19	STRAIN GAUGES ELECTRONIC CIRCUITS	361
19.1	Signal Conditioning for Force Transducers	361
19.2	Signal Conditioners.....	362
19.2.1	Pre- and Post-Conditioning.....	362
19.2.2	High-Gain Signal Conditioning	363
19.2.3	“QuantumX” Universal Conditioner.....	363

19.3 Analog-to-Digital Converters 365

19.3.1 Different Conversions to Frequency 365

19.3.2 Resistance-to-Time Converter 365

19.3.3 Sigma-Delta Converter 366

19.4 Bridge Oscillators 367

19.4.1 Wien Bridge Based Oscillator 367

19.4.2 Wheatstone Bridge Based Oscillator 368

19.5 AC Generators 369

19.5.1 Sine Wave Generator 369

19.5.2 Saw-Tooth Wave Generator 369

19.5.3 Rectangular Wave Generator 370

19.6 Strain Gauged Force Transducers Connected to PC 371

19.6.1 Direct Resistance Change Measurement 371

19.6.2 Strain Gauge Bridge Signal Processing 371

REFERENCES 373

20 CLASSIFICATION OF ELASTIC ELEMENTS..... 375

20.1 Elastic Elements Loading Modes 375

20.2 Examples of Elastic Elements Classifications 378

20.3 Comprehensive Classification of Elastic Elements 381

REFERENCES 387

21 STRETCHED / COMPRESSED COLUMNS 389

21.1 Classical Columns 389

21.2 Optimized Columns 394

21.3 Increasing Sensitivity for Columnar Transducers..... 394

21.4 Complex Structures Composed by Bars / Columns..... 395

21.5 Dynamic Testing for Cylindrical Transducers..... 396

REFERENCES 397

22 STRETCHED / COMPRESSED TUBES..... 399

22.1 Classical Tubes 399

22.2 Concentric Tubes 403

22.3 Profiled Tubes..... 404

22.4 Tubes with Holes or Slots 408

22.5 Tubular Structures under Complex Loading 410

REFERENCES 411

23 BENT LAMELLA (CANTILEVER BEAMS)..... 415

23.1 Various Applications with Cantilever Beams 415

23.2 Cantilever Beams for Lower Forces 419

23.3 (Bio)Chemical Cantilevers..... 424

23.4 Several Shapes of Cantilever Beams 428

23.5 Cantilever Beams in Multicomponent FTs 431

REFERENCES 434

24	BENT AND/OR TORSION SHAFTS.....	437
24.1	Bending of Cantilever Tube or Cylinder.....	437
24.2	Rotating Shafts.....	439
24.3	Complex Loaded Shafts.....	441
	REFERENCES	443
25	MIDDLE BENT BARS WITH FIXED ENDS	445
25.1	Examples of Middle Bent Bars with Fixed Ends	445
25.2	Slotted Structures for Middle Bent Bars with Fixed Ends	448
25.3	Dynamic Applications of Double Ended Beams.....	450
25.4	Various Models of Four-Spoke Wheels.....	452
	REFERENCES	455
26	SHEARING STRAINED ELASTIC ELEMENTS.....	457
26.1	'I'-Profiles Subjected to Shearing.....	459
26.2	Load Measuring Pins / Bolts.....	460
26.3	Hollow Discs / Wheels.....	462
26.4	S (Z) Shaped Elastic Elements.....	464
26.5	Helix Load Cells	465
	REFERENCES	466
27	BENT YOKES AND FRAMES.....	469
27.1	Various Shapes of Bent Yokes and Frames	471
27.2	Force-Measuring Clamps	474
	REFERENCES	475
28	BENT RINGS AND "GLASSES"	477
28.1	Various Shapes of Bent Rings	477
28.1.1	Circular Rings	477
28.1.2	"Square" Rings.....	480
28.1.3	Hexagonal Rings.....	481
28.1.4	Octagonal Rings.....	481
28.1.5	Other Shapes of Bent Rings.....	482
28.2	"Glasses"-Shaped Elastic Structures.....	484
28.3	Multiple "Glasses"-Shaped Elastic Elements	490
	REFERENCES	491
29	BENT MEMBRANES.....	495
29.1	Various Types of Bent Membranes	495
29.2	Circular Membranes.....	500
29.3	Square Membranes.....	505
29.4	Membranes with Various Shapes of Apertures.....	509
29.5	Other Shapes of Membranes	511
	REFERENCES	514

30 COMPLEX LOADED TORUS..... 517
30.1 Torus as Elastic Element for Force Transducers..... 517
30.2 Toroidal Elastic Elements in Special Applications 520
REFERENCES 522

31 AXISYMMETRIC ELASTIC ELEMENTS..... 523
31.1 Various Axisymmetric EEs for Force Transducers..... 523
31.2 Axisymmetrical EEs for Very Large Force Transducers 528
31.3 N-Shaped Axisymmetric Elastic Elements 534
REFERENCES 537

32 VOLUMETRIC ELASTIC ELEMENTS..... 539
32.1 Spheres..... 539
32.2 Cubes 542
32.2.1 Full Cubes 542
32.2.2 Cubic Blocks with Slots..... 543
32.3 Complex Bodies with Oblique Slots 547
REFERENCES 548

33 COMPLEX, COMPOSED AND COMBINED ELASTIC STRUCTURES 549
33.1 Complex Elastic Structures..... 550
33.1.1 Plane Complex Structures 550
33.1.2 Spatial Complex Structures..... 552
33.2 Composed Elastic Structures 554
33.3 Combined Elastic Structures..... 558
33.3.1 Plane Combinations of Elastic Elements..... 558
33.3.2 Axisymmetric Combinations of Elastic Elements..... 559
33.3.3 Spatial Combinations of Elastic Elements 560
REFERENCES 562

34 ELASTIC ELEMENTS SELECTION CRITERIA 563
34.1 Elastic Elements (EEs) Evaluation Criteria 565
34.2 Elastic Elements Comparative Analysis 566
34.3 EE Selection for Specific Applications..... 569
34.3.1 From Single- to Multi-component Force Transducers 569
34.3.2 Force Transducers in Mechatronics 570
34.3.3 EEs for Very Large Forces..... 571
34.4 Elastic Elements Automatic Selection 572
REFERENCES 574

35	DIGITAL AND INTELLIGENT FORCE TRANSDUCERS.....	577
35.1	Evolution from Analog to Digital	577
35.2	Automatic Recognition of Force Transducers	579
35.3	Force Transducers in Dynamic Regime	581
35.4	Intelligent (Smart) Force Transducers	582
35.5	Further Prospects: Materials, Technologies, Ideas.....	583
35.5.1	Smart Materials and Structures.....	583
35.5.2	Intelligent Design and Smart Technology	584
35.5.3	Neuro-Fuzzy Concepts	585
35.6	Updated Force Transducers + Data Communication.....	585
35.6.1	Dual Output Force Transducers	585
35.6.2	Data Display and Communication	587
	REFERENCES	589
ANNEX 1.	Rules for Strain Gauges Placement on the Elastic Elements of Force Transducers.....	591
ANNEX 2.	The Newton's Apple Tree in Korea	595
INDEX		597