

Contents

List of Figures	xi
List of Tables	xiii
List of Abbreviations	xv
List of Symbols	xvii
1 Introduction	1
1.1 Background	1
1.2 Rendezvous and Docking	2
1.3 Proximity Operations	4
1.4 Literature Review	5
1.4.1 Six-DOF Proximity Operations Based on Two Decoupled Three-DOF Motions	5
1.4.2 Six-DOF Proximity Operations Based on Two Coupled Three-DOF Motions	8
1.4.3 Six-DOF Proximity Operations Based on Coupled Dynamic Model Using Dual Quaternions	11
1.5 Research Gaps and Motivation	13
1.6 Research Approach	14
1.6.1 Research Methodology	14
1.6.2 Outline of the Dissertation	14
2 Fundamentals	17
2.1 Attitude of a Rigid Body	17
2.1.1 Different Attitude Representations	17
2.1.2 Quaternion Algebra	19
2.1.3 Unit Quaternion-Based Attitude Representation	23
2.1.4 Unit Quaternion Kinematics	24
2.1.5 Rodrigues Parameter Kinematics	25
2.1.6 Modified Rodrigues Parameter Kinematics	26
2.1.7 Dynamic Equations of Rotational Motion	26
2.2 Translation and Rotation (Pose) of Rigid Body	26
2.2.1 General Spatial Displacement of a Rigid Body and $SE(3)$	26
2.2.2 Dual Quaternion Algebra	27
2.2.3 Rigid Body Motion Based on Dual Quaternion	30
2.2.4 Relative Motion Based on Dual Quaternions	33

2.3	Sliding Mode Control	35
2.3.1	Sliding Mode	36
2.3.2	Reachability Condition of Sliding Mode	38
2.3.3	Control Form of SMC	39
2.3.4	Robustness in Sliding Mode	40
2.3.5	Chattering	41
2.4	Control Theory Related	43
2.4.1	Lemma for Finite-Time Stability	43
3	Potential Field-Based Sliding Surface Design for Spacecraft Attitude Maneuvers	45
3.1	Literature Review	45
3.2	Methodology	46
3.3	Potential Field-Based Sliding Surface Design	47
3.3.1	Results Based on Unit Quaternions	47
3.3.2	Results Based on Rodrigues Parameters	48
3.3.3	Results Based on Modified Rodrigues Parameters	49
3.3.4	Possible New Result of Sliding Surface	51
3.4	Conclusion	51
4	Potential Field-Based Sliding Mode Control for Spacecraft Reorientation with Attitude Constraints	53
4.1	Literature Review	53
4.2	Attitude Constraints	55
4.2.1	Attitude Forbidden Zone	56
4.2.2	Attitude Mandatory Zone	57
4.3	Controller Design	58
4.3.1	Sliding Surface Design	58
4.3.2	Analysis of Critical Points of Potential Field in Sliding Mode	60
4.3.3	Sliding Mode Control Based on Artificial Potential Field	63
4.4	Simulation Results	66
4.5	Conclusion	75
5	Adaptive Sliding Mode Control for Spacecraft Proximity Operations Based on Dual Quaternions	77
5.1	Sliding Mode Control Design	77
5.1.1	Sliding Surface Design Based on Dual quaternions	77
5.1.2	Control Law Design	79
5.1.3	Modification for the Unwinding Phenomenon	83
5.1.4	Chattering Alleviation	84
5.2	Simulation Results	84
5.3	Conclusion	90

6	Spacecraft Proximity Operations with Motion Constraints Based on Dual Quaternions	95
6.1	Motion Constraints	95
6.1.1	FOV Constraint	95
6.1.2	Approach Path Constraint	97
6.2	APF-Based Sliding Mode Control Design	98
6.2.1	Design of APF Based on Dual Quaternion	98
6.2.2	Sliding Variable Design Based on APF	99
6.2.3	Analysis of Critical Points of Potential Field in Sliding Mode	100
6.2.4	Sliding Mode Control Law Design	102
6.3	Simulation Results	106
6.3.1	Results Based on Normal Dual Quaternion-Based SMC	108
6.3.2	Results Based on APF-based SMC and APF-based PD	108
6.4	Conclusion	112
7	Conclusions and Outlook	119
7.1	Conclusions	119
7.2	Outlook	120
	Bibliography	123