

Contents

Abstract	xi
Kurzfassung	xiii
1 Introduction to flow metering	1
1.1 Importance of flow metering and available devices	1
1.2 Ultrasonic transit-time devices	3
1.2.1 Classification of designs	4
1.2.2 Wave-path configurations	5
1.2.3 Normally vs. obliquely radiating transducers	7
1.2.4 Volumetric flow rate determination	7
1.2.5 Temperature compensation	9
1.2.6 Challenges and requirements for UFM water meters	10
1.3 Proposed design: Lamb wave-based flow metering	12
1.4 Goal and structure of this monograph	14
2 Elastodynamic field theory	17
2.1 Elastodynamic field in time-space domain	17
2.1.1 Fundamental equations of elastodynamics	17
2.1.2 Constitutive relations	19
2.1.3 Navier's equation: elastodynamic waves	21
2.1.4 Acoustics	22
2.1.5 Boundary and interface conditions	23
2.2 Elastodynamic field in frequency-wave vector domain	26
2.2.1 Fourier transforms	26
2.2.2 Governing equations in frequency-wave vector domain	27
2.2.3 Energy density	28
2.2.4 Power flux density: the elastodynamic Poynting vector	29
2.2.5 Equipartition of energy	29
2.2.6 Complex reciprocity relations	30
2.3 Homogeneous and inhomogeneous plane waves	31
2.3.1 Dispersion relations	33
2.3.2 Energy velocity	37
2.3.3 Group velocity	39
2.4 Concluding remarks	40
3 Guided and quasi-guided waves	43
3.1 Guided waves in plates	43
3.1.1 Waveguide problem formulation	44
3.1.2 Dispersion curves of an anisotropic plate	45

3.1.3	Classification of modes	47
3.1.4	Dispersion curves of an isotropic plate	50
3.1.5	Wave field of Lamb modes	52
3.1.6	Power flux considerations	53
3.1.7	Orthogonality relations between modes	55
3.1.8	Excitation of guided waves	56
3.1.9	Perturbation theory	59
3.2	Quasi-guided waves in fluid-coupled plates	60
3.2.1	Models for the fluid-coupled plate	60
3.2.2	QGW problem formulation	65
3.2.3	Polynomial form of the QGW problem through change of variable	69
3.2.4	Structure of the QGW problem	70
3.2.5	Classification of waves	72
3.2.6	Dispersion of quasi-guided waves	76
3.2.7	Wave field of trapped and leaky waves	79
3.2.8	Radiation	85
3.2.9	Immersed plate: double sided fluid coupling	89
3.2.10	Strongly fluid-loaded plate	91
4	Numerical Solution Methods	93
4.1	Solving waveguide problems	93
4.1.1	Root-finding of the characteristic equation	93
4.1.2	Eigenvalue problem discretization	96
4.2	Spectral collocation for waveguide problems	97
4.2.1	Chebyshev spectral collocation method	97
4.2.2	Discretization of the quasi-guided wave problem	98
4.2.3	Integration on Chebyshev-Gauß-Lobatto points	102
4.3	Polynomial eigenvalue problems	102
4.4	Elastodynamic Acoustic Toolbox (EDAT)	104
5	Experimental methods and verification	105
5.1	Transducers for waveguide excitation and sensing	105
5.1.1	Bonded piezoelectric ceramics	106
5.1.2	Comb array and comb transducers	108
5.2	Laser Doppler measurement of waveguide spectra	109
5.3	Schlieren photography	117
6	Modeling Lamb wave-based flow meters	121
6.1	Convection of ultrasound: ray tracing	121
6.2	Time-of-flight model of flow meters	123
6.2.1	Lamb wave-based flow meter	124
6.2.2	Piston type transducer-based flow meter	127
6.2.3	Comparison of flow meter setups and models	129

6.3	Incidence and reflection from the pipe wall	131
6.3.1	Excitation of a leaky Lamb wave by an incident acoustic beam	131
6.3.2	Nonspecular reflection from the pipe wall	135
7	Sensitivity and interference errors	141
7.1	Flow meter sensitivity to flow rate	141
7.2	Flow rate cross-sensitivities	141
7.3	Waveguide parameter cross-sensitivities	144
7.3.1	Thickness and frequency: Abrasion and manufacturing tolerances	144
7.3.2	Mechanical parameters: Material uncertainty and aging	145
7.3.3	Deposited layer: Scaling and dezincification	146
7.4	Temperature cross-sensitivity	150
7.4.1	Temperature dependence of the pipe material	151
7.4.2	Temperature dependence of the fluid wave speed	152
7.4.3	Overall differential effect of temperature	154
7.5	Flow meter sensitivity including temperature	156
8	Flow meter: model validation and measurements	159
8.1	Validation: experimental data of a prototype	159
8.1.1	LDV measurements	159
8.1.2	Ultrasonic pitch-catch measurements	161
8.2	Flow rate determination from the V-path	166
8.3	Temperature determination from direct path	169
8.4	A general inversion method: compensation of arbitrary effects	171
9	Conclusions and outlook	175
A	Appendix: Material data	179
	Bibliography	181
	References	181
	Publications	198
	List of supervised student theses	201
	Table of symbols	203