

Contents

1	Introduction	1
1.1	Motivation	1
1.2	Literature overview	3
1.3	Research objectives	5
1.4	Outline	6
2	Theoretical framework	9
2.1	Stability of dynamical systems	9
2.2	Floquet theory	11
2.3	Lyapunov characteristic exponents	13
2.4	Parametric resonance effects	15
2.4.1	Synchronous excitation	15
2.4.2	Asynchronous excitation	17
2.5	The method of normal forms	19
3	Global stability effects of asynchronous parametric excitation	25
3.1	Investigated systems	25
3.2	Displacement-proportional excitation	27
3.2.1	Normal form for non-resonant parametric excitation: system I . .	27
3.2.2	Conditions for the existence of global effects: system I	28
3.2.3	Stabilizing and destabilizing global effects: system I	29
3.3	Velocity-proportional excitation	34

3.3.1	Normal form for non-resonant parametric excitation: system II . . .	34
3.3.2	Conditions for the existence of global effects: system II	35
3.3.3	Stabilizing and destabilizing global effects: system II	35
3.4	Combined displacement- and velocity-proportional excitation	38
3.4.1	Normal form for non-resonant parametric excitation: system III .	38
3.4.2	Conditions for the existence of global effects: system III	39
3.4.3	Stabilizing and destabilizing global effects: system III	40
3.5	Conclusions	42
4	Coexistence of resonance and anti-resonance	45
4.1	Displacement-proportional excitation: $\mathbf{MDK} + \mathbf{C}(t)$ system	46
4.1.1	Parametric anti-resonance	48
4.1.2	Parametric resonance	49
4.1.3	Simultaneous parametric resonance and anti-resonance	49
4.2	Displacement-proportional excitation: $\mathbf{MDGKN} + \mathbf{C}(t)$ system	56
4.2.1	$\mathbf{MDKGN} + \mathbf{C}(t)$ system with given phase relations	58
4.2.2	Discussion	61
4.3	Velocity-proportional excitation: $\mathbf{MDK} + \mathbf{B}(t)$ system	64
4.3.1	Parametric anti-resonance	66
4.3.2	Parametric resonance	67
4.3.3	Simultaneous parametric resonance and anti-resonance	67
4.4	Simultaneous displacement- and velocity-proportional excitation	72
4.5	Conclusions	74
5	Simulation-based validation of coexistence	75
5.1	Introduction	75
5.2	Electronic system design	77
5.3	Validation of the theoretical findings	80
5.4	Conclusions	83

6	Fundamental resonances	85
6.1	MDK + $C(t)$ system	86
6.2	MDGKN + $C(t)$ system	89
6.3	Conclusions	92
7	Asynchronous parametric excitation in nonlinear systems	95
7.1	Analyzed system	95
7.2	Non-resonant parametric excitation	96
7.3	Combination resonances	97
7.4	Conclusions	101
8	Mechanical examples	103
8.1	Rotating Disk	103
8.1.1	Problem definition	103
8.1.2	Stability analysis	105
8.1.3	Conclusions	107
8.2	Minimal model of a disk brake with asymmetric mounting	108
8.2.1	Problem definition	108
8.2.2	Stability analysis	110
8.2.3	Conclusions	118
9	Conclusion	121