

Contents

Preface — V

1	Introduction to Intelligent Materials and Structures — 1
1.1	Types of Intelligent Materials — 1
	References — 21
1.2	Extended Review on Piezoelectric Materials, SMA, ER and MR Fluids and MS and ES Materials — 24
1.2.1	Extended Review on Piezoelectricity — 24
1.2.2	Extended Review on Shape Memory Alloys — 28
1.2.3	Extended Review on Electrorheological and Magnetorheological Fluids — 29
1.2.4	Extended Review on Magnetostrictive and Electrostrictive Materials — 30
	References – Piezoelectricity — 31
	References – Shape Memory Alloys — 46
	SMA Reinforced Plates and Shell-Related References — 50
	References – Electrorheological and Magnetorheological Fluids — 53
	References – Magnetostrictive and Electrostrictive Materials — 61
1.3	Typical Properties of Intelligent Materials — 66
	References — 77
1.4	Recent Applications of Intelligent Materials and Systems — 78
	References — 85
2	Laminated Composite Materials — 88
2.1	Classical Lamination Theory — 88
2.1.1	Introduction — 88
2.1.2	Displacements — 89
2.1.3	Strain — 90
2.1.4	Stress — 90
2.1.5	Orthotropic Materials — 90
2.1.6	Unidirectional Composites — 92
2.1.7	Properties of a Single Ply — 94
2.1.8	Transformation of Stresses and Strains — 94
	References — 102
2.2	First-Order Shear Deformation Theory (FSDT) Model — 102
	References — 107
2.3	Appendix I — 113
2.3.1	Appendix A — 113

3	Piezoelectricity — 115
3.1	Constitutive Equations — 115
3.1.1	Classification of Dielectric Materials — 115
3.1.2	Important Dielectric Parameters — 117
3.2	Pin Force Beam Model — 137
3.3	Uniform-Strain Beam Model — 150
3.4	Bernoulli–Euler Beam Model — 161
	References — 172
3.5	First-Order Shear Deformation (Timoshenko-Type) Beam Model — 172
3.5.1	Solutions for Static and Dynamic Cases — 179
3.5.2	Calculation of the Axial Induced Force due to E_{11}^0 — 179
3.5.3	Solution of the Equations of Motion for Small Lateral Vibrations — 182
3.5.4	Solution of the Static Case — 186
3.5.5	Experimental Validation for the Induced Axial Force Case — 191
	References — 192
3.6	Composite Plates with Piezoelectric Patches — 193
	References — 210
3.7	Appendix A — 211
3.7.2	Appendix B — 214
3.7.3	Appendix C: Constants Presented in Table 3.4 — 215
3.7.4	Appendix D: Constants Presented in Table 3.5 — 215
3.7.5	Appendix E — 216
	References — 216
4	Shape Memory Alloys — 218
4.1	Basic Behavior of SMA — 218
4.1.1	The Shape Memory Effect — 222
4.1.2	Pseudoelasticity — 224
4.1.3	Applications — 225
	References — 232
4.2	Constitutive Equations — 233
4.2.1	One-Dimensional Constitutive Equations for an SMA Material — 233
	References — 241
4.2.2	Heating an SMA Material Using Electrical Current — 239
4.3	SMA Models in Literature — 242
	References — 249
5	Electrorheological and Magnetorheological Fluids — 251
5.1	Fundamental Behavior of ER and MR Fluids — 251
	References — 264

5.2	Modeling ER and MR Fluids — 265
	References — 275
5.3	Damping of ER and MR Fluids — 276
	References — 287
5.4	Appendix III — 290
5.4.1	Appendix A — 290
5.4.2	Appendix B — 291
5.4.3	Appendix C — 292
6	Magnetostrictive and Electrostrictive Materials — 294
6.1	Behavior of Magnetostrictive Materials — 294
	References — 302
6.2	Constitutive Equations of Magnetostrictive Materials — 302
6.2.1	One-Dimensional Model — 307
	References — 310
6.3	Behavior of Electrostrictive Materials — 310
	References — 315
6.4	Constitutive Equations of Electrostrictive Materials — 315
	References — 323
6.5	Appendix IV — 324
6.5.1	Appendix A — 324
6.5.2	Appendix B — 326
7	Applications of Intelligent Materials in Structures — 333
7.1	Aerospace Sector — 333
	References — 354
7.2	Medical Sector — 355
	References — 361
7.3	Piezoelectric Motors — 361
7.3.1	Linear Piezoelectric Motors — 364
7.3.2	Rotary Piezoelectric Motors — 365
7.3.3	Ultrasonic Piezomotor – Characteristics and Classification — 366
7.3.4	Ultrasonic Piezomotors: Operating Principles — 373
	References — 374
8	Energy Harvesting Using Intelligent Materials — 377
8.1	Piezoelectric Energy Harvesting — 377
	References — 391
8.2	Electromagnetic Energy Harvesting — 393
	References — 400
8.3	Bimorph Electrical Power Under Vibration Excitation — 401
8.4	Piezoelectric Harvester with Enhanced Frequency Bandwidth — 407

8.4.1	Introduction —	407
8.4.2	Derivation of the Equations of Motion and Their Solution —	408
8.4.3	Numerical Validation —	414
8.4.4	Experimental Validation —	415
8.4.5	Three Versus Two Bimorph Systems —	423
8.4.6	Conclusions and Recommendations —	424
	References —	425
9	Introduction to Fiber Optic —	429
9.1	Geometrical Optics: Basic Concepts —	429
9.1.1	Reflection of Light —	429
9.1.2	Snell's Law – Refractions —	430
9.1.3	Critical Angle and Total Internal Reflection —	430
9.1.4	Numerical Aperture and Acceptance Angle of a Fiber —	431
9.1.5	Interference —	433
9.1.6	Diffraction Grating for Light Waves —	434
9.2	Basic Characteristics of a Fiber Optic —	435
9.3	Fiber Optic – Historical Aspects —	440
9.4	Fiber Bragg Grating (FBG) —	443
9.5	Fiber Bragg Grating Used as Strain Sensor —	446
9.6	Interrogators for Fiber Bragg Grating —	447
	References —	447
10	Miscellaneous Topics —	450
10.1	Enhanced Flexural Behavior of Plates Equipped with SMA Wires —	450
10.1.1	The Use of SMA Properties for Actuation: The Restrained Recovery Phenomena —	450
10.1.2	Experimental Results —	452
10.2	Piezoelectric Fiber Composite —	459
10.2.1	PZT Fibers —	459
10.2.2	PVDF Copolymer Fibers —	463
10.3	Acoustic Energy Harvesting —	465
10.3.1	Acoustic Basics —	465
10.3.2	Acoustic Power Augmentation —	466
10.4	Harvesting Using SMA —	467
10.4.1	Magnetic Shape Memory Alloys —	467
10.4.2	SMA and MSMA Harvesting —	468
10.5	Road Traffic Harvesting Using Piezoelectric Transducers —	469
	References —	472