

Inhaltsverzeichnis

Development of a flexible special kinematics for the fully mechanized production of tubular nodes for offshore foundation structures

Hagen Herholz, Steffen Dryba, Mirko Gründler and Martin-Christoph Wanner

Enabling Domain Experts to Model and Execute Tasks in Flexible Human-Robot Teams

Dominik Riedelbauch, Tobias Werner and Dominik Henrich

Virtual Testbeds for the Development of Sensor-Enabled Applications

Jörn Thieling and Jürgen Roßmann

Cloud-based Plant and Process Monitoring based on a Modular and Scalable Data Analytics Infrastructure

Ilja Maurer, Mauro Riva, Christian Hansen and Tobias Ortmaier

Normal Operation Input Signals for Parameter Estimation in Underactuated Structures

Gunnar Borchert, Jonas Diekmeyer, Konrad Bild and Annika Raatz

Joining Linked Micro Formed Parts through Tolerance Field Widening and Synchronization

Ann-Kathrin Onken, Patrick Rückert, Christian Perl and Kirsten Tracht

Combined Structural-Dimensional Synthesis of Robot Manipulators for Minimal Energy Consumption

Daniel Ramirez, Jens Kotlarski and Tobias Ortmaier

Development of a modular framework for contact force models

Tobias Osterloh and Jürgen Roßmann

Development of a Methodology for the Determination of Conceptual Automated Disassembly Systems

Julius Wolff, Torge Kolditz, Lutz Günther and Annika Raatz

Feature Recognition, Sub-Path Creation and Sequence Optimization in Systems for Processing of 2.5D Workpieces During Throughput

Denise Klose, Martin Ketels and Thorsten Schüppstuhl

Design and Evaluation of a Multi-Agent Software Architecture for Risk-Minimized Path Planning in Human-Robot Workcells

Tobias Werner, Dominik Riedelbauch and Dominik Henrich

Challenges of the Miniaturization in the Electronics Production on the example of 01005 components

Jens Niemann, Stefan Härter, Christopher Kästle and Jörg Franke

Boundary Conditions in Handling of Microspheres Induced by Shape Deviation Constraints

Finn Meiners, Sebastian Hogreve and Kirsten Tracht

Continuous Digitalization of Rotationally Symmetrical Components With a Lateral Scanning White Light Interferometer

Sönke Bahr, Marc-André Otto, Tomas Domaschke and Thorsten Schüppstuhl

Towards a Mobile Robotic Assembly System Using a Compliant Robot

Ulrich Berger, Duc Tho Le, Wenchao Zou and Mayur Andulkar

Task-based Simulation Tool for Human-Robot Collaboration within Assembly Systems

Paul Glogowski, Kai Lemmerz, Lena Schulte, Andre Barthelmey, Alfred Hypki, Bernd Kuhlenkötter and Jochen Deuse

Centralized vs. decentralized storage of semantic definitions used for data exchange within the CAX toolchain

Matthias Bartelt and Bernd Kuhlenkötter

Behavior Trees for Task-Level Programming of Industrial Robots

Akos Csiszar, Martin Hoppe, Shahbaz A. Khader and Alexander Verl

Work Space Layout and Evaluation Using the Elbedome 2.0 Virtual Environment

Michael Schenk and Steffen Masik

Automated handling of high-temperature thermoplastic Carbon Fiber materials for a large-scale production

Johannes Graf, Christoph Richter and Gunther Reinhar