

Contents

1	Introduction	1
1.1	Basic Idea and Main Task of Photogrammetry	1
1.2	Why Photogrammetry?	3
1.3	Image Sources: Analogue and Digital Cameras	3
1.4	Digital Consumer Cameras	5
1.5	Short History of Photogrammetric Evaluation Methods	6
1.6	Geometric Principles 1: Camera Position, Focal Length	7
1.7	Geometric Principles 2: Image Orientation	9
1.8	Geometric Principles 3: Relative Camera Positions (Stereo)	11
1.9	Some Definitions	12
1.10	Length and Angle Units	13
1.11	A Typical Workflow in Photogrammetry	14
2	Included Software and Data	17
2.1	Hardware Requirements, Operating System	17
2.2	Image Material	18
2.3	Overview of the Software	18
2.4	Installation	19
2.5	General Remarks	20
3	Scanning of Photos	21
3.1	Scanner Types	21
3.2	Geometric Resolution	22
3.3	Some Practical Advice	23
3.4	Import of the Scanned Images	23
4	A Single Model	25
4.1	Project Definition	25
4.2	Orientation of the Images	26
4.2.1	Camera Definition	26
4.2.2	Interior Orientation	28
4.2.3	Brightness and Contrast	31

4.2.4	Control Points	32
4.2.5	Exterior Orientation	34
4.2.6	Over-Determination and Error Detection	37
4.3	Model Definition	38
4.4	Stereoscopic Viewing	40
4.5	Measurement of Object Co-ordinates	42
4.6	Creation of DTMs via Image Matching.	44
4.6.1	Some Theory	44
4.6.2	Practical Tests	49
4.6.3	Additional Manual Measurements.	51
4.6.4	Quality Control	51
4.7	Ortho Images	52
4.7.1	Some Theory	52
4.7.2	Resampling Methods	54
4.7.3	Practical Tests	55
4.7.4	Creation and Overlay of Contours	56
4.7.5	Simple 3D Data Collection	58
5	Aerial Triangulation	61
5.1	Aerial triangulation measurement (ATM)	61
5.1.1	Common Principles	61
5.1.2	Interior Orientation	62
5.1.3	Manual Measurement	63
5.1.4	Automatic Measurement via Image Matching: Introduction.	67
5.1.5	Co-ordinate Input and Measurement of Ground Control Points	67
5.1.6	Strip Definition	68
5.1.7	Measurement of Strip Connections	71
5.1.8	Automatic Image Co-ordinate Measurement (AATM)	72
5.2	Block Adjustment with BLUH.	75
5.2.1	Introduction.	75
5.2.2	Running the Block Adjustment	76
5.2.3	Discussion of the Results	78
5.2.4	Improvement of Strip Connections	83
5.2.5	Second Run of BLUH	84
5.2.6	Additional Analysis of the Results	84
5.3	Mosaics of DTMs and Ortho Images	88
5.3.1	Model Definition	88
5.3.2	Creation of a DTM Mosaic	88
5.3.3	Creation of an Ortho Image Mosaic	88
5.3.4	Shaded Relief	89
5.3.5	Contour Lines Overlay	90
5.3.6	3D View.	91

6	A Soil Erosion Experiment	93
6.1	The Situation.	93
6.2	Interior and Exterior Orientation	94
6.3	Model Definition, Start Points	95
6.4	DTM Creation	96
6.5	Differential DTM	97
7	Wave Measurements	99
7.1	The Situation.	99
7.2	Interior and Exterior Orientation	101
7.3	Model Definition	104
7.4	DTM Creation	104
7.5	Image Sequences	106
8	Lens Distortion and Calibration	109
8.1	Introduction.	109
8.2	Lens Calibration	111
8.3	A Simple Self-made Model	113
9	Two Final Examples	115
9.1	Stereo Images from Satellites.	115
9.2	Stereo Images from Flatbed Scanners	117
9.3	A View into the Future.	119
10	Programme Description	121
10.1	Some Definitions	121
10.2	Basic Functions	121
10.3	Limitations	122
10.4	Operating the Programmes	122
10.5	Buttons in the Graphics Windows	123
10.6	LISA BASIC.	123
10.6.1	File > Select Project	124
10.6.2	File > Define Project	124
10.6.3	File > Edit Project	124
10.6.4	File > Import	125
10.6.5	File > Export	126
10.6.6	Vector Data > Control Points.	126
10.6.7	Vector Data > Define Symbols.	126
10.6.8	Vector Data > Projections	127
10.6.9	Vector Data > Vector → Raster	127
10.6.10	Image Processing > Two-Dimensional Histogram.	128
10.6.11	Image Processing > Rectification	128
10.6.12	Image Processing > Mosaic	131
10.6.13	Image Processing > Classification.	131
10.6.14	Image Processing > Matching	131
10.6.15	Image Processing > Area Symbols	133

- 10.6.16 Terrain Models 133
- 10.6.17 Terrain Models > Interpolation..... 134
- 10.6.18 Terrain Models > Filtering..... 135
- 10.6.19 Terrain Models > Contour Lines Vector 135
- 10.6.20 Terrain Models > Numerical Evaluation 136
- 10.6.21 Terrain Models > Matching..... 136
- 10.6.22 Analysis 137
- 10.6.23 Data Base 137
- 10.6.24 Display Raster Image 137
- 10.6.25 Display Vector Graphics 142
- 10.6.26 Display Text 144
- 10.6.27 Display Attributes 144
- 10.7 LISA FOTO 145
 - 10.7.1 File > Select, Define or Edit Project 145
 - 10.7.2 File > Import..... 145
 - 10.7.3 Pre Programmes > Camera Definition 146
 - 10.7.4 Pre Programmes > Control Points..... 148
 - 10.7.5 Pre Programmes > Strip Definition 148
 - 10.7.6 Pre Programmes > Orientation > Measure >
Interior Orientation 148
 - 10.7.7 Pre Programmes > Orientation > Measure >
Exterior Orientation 150
 - 10.7.8 Pre Programmes > Orientation > Measure >
Calibration Pattern 151
 - 10.7.9 Pre Programmes > Parameters of the Exterior
Orientation 152
 - 10.7.10 Pre Programmes > Select Model 152
 - 10.7.11 Pre Programmes > Define Model 152
 - 10.7.12 Aerial Triangulation Measurement (ATM)..... 154
 - 10.7.13 ATM > Manual Measurement 154
 - 10.7.14 ATM > Calculate Strip Images 157
 - 10.7.15 ATM > Measure Connections 157
 - 10.7.16 ATM > Automatic Measurement (AATM)..... 159
 - 10.7.17 ATM > Export > BLUH..... 160
 - 10.7.18 Processing > Stereo Measurement 161
 - 10.7.19 Processing > Stereo Correlation (Matching)..... 163
 - 10.7.20 Processing > DTM Interpolation..... 164
 - 10.7.21 Processing > Ortho Image 164
 - 10.7.22 Processing > Camera Positions..... 165
 - 10.7.23 Processing > Image Sequences..... 165
 - 10.7.24 Display Raster Image 166
 - 10.7.25 Display Text 166

10.8	Aerial Triangulation with BLUH	166
10.8.1	Pre Processing > Select Project, Define Project	166
10.8.2	Pre Processing > Control Point Editor.	167
10.8.3	Pre Processing > Strip Definition	167
10.8.4	Pre Processing > Photo Co-ordinates Editor.	167
10.8.5	Block Adjustment > Strategy.	167
10.8.6	Block Adjustment > the Central BLUH Modules	168
10.8.7	Block Adjustment > All (Batch).	169
10.8.8	Block Adjustment > Analysis (BLAN)	169
10.8.9	Display Graphics	170
10.8.10	Display Text	170
10.8.11	Some More Theory	170
10.9	LISA FFSAT	172
10.9.1	Introduction.	172
10.9.2	Image Sources	173
10.9.3	File > Select, Define or Edit Project	173
10.9.4	File > Import	173
10.9.5	Pre Programmes > Sensor Definition	174
10.9.6	Pre Programmes > Orientation Measurement	174
10.9.7	Processing > Stereo Measurement, Correlation, DTM Interpolation	175
10.9.8	Processing > Ortho Image	175
Appendix		177
Glossary		199
References		203
Index		207