

Contents

Part I Fundamentals

1	Basic Forms of Model Representation	3
1.1	Objectives	3
1.2	The General Modelling Approach	5
1.3	Physical Modelling, Analogies, and Bond Graphs	6
1.4	Block Diagrams	10
1.5	Symbolic Model Solving	11
1.6	The Object-Oriented Approach	12
1.7	Computer Aided Modelling	15
1.8	The Book Summary	19
	References	21
2	Bond Graph Modelling Overview	23
2.1	Introduction	23
2.2	Word Models	23
2.3	Ports, Bonds, and Power Variables	24
2.4	Component Model Development	26
2.5	Modelling Basic Physical Processes	28
2.5.1	Elementary Components	28
2.5.2	The Inertial Components	29
2.5.3	The Capacitive Components	30
2.5.4	The Resistive Components	31
2.5.5	The Sources	32
2.5.6	The Transformers and Gyrators	33
2.5.7	The Effort and Flow Junctions	34
2.5.8	Controlled Components	35
2.6	Block Diagram Components	37
2.6.1	Introduction	37
2.6.2	Continuous-Time Components	38
2.6.3	Discrete-Time Components	40

2.7	Modelling Simple Engineering Systems.	43
2.7.1	Simple Body Spring Damper System.	43
2.7.2	The Simple Electrical Circuit	48
2.7.3	A See-Saw Problem	53
2.8	Causality of Bond Graphs	63
2.8.1	The Concept of Causality.	63
2.8.2	Causalities of Elementary Components	64
2.8.3	The Procedure for Assigning Causality	67
2.9	The Formulation of the System Equations	69
2.10	The Causality Conflicts and Their Resolution.	72
	References	75
3	An Object-Oriented Approach to Modelling	77
3.1	Introduction	77
3.2	The Component Model	77
3.2.1	The Component Class	78
3.2.2	The Document Class	79
3.3	The Component Class Hierarchy	83
3.4	Port and Bond Classes	85
3.5	Description of the Element Constitutive Relations.	89
3.6	Modelling Vector and Higher-Dimensional Quantities	90
3.7	Port Connection Rules.	92
3.8	The Component Set Classes.	95
3.9	Systematic Top/Down Model Development	97
3.10	Component Libraries and Model Reuse	100
	References	102
4	Object Oriented Modelling in a Visual Environment	105
4.1	Introduction	105
4.2	The Visual Environment	106
4.3	The Component Hierarchy.	110
4.4	The Port and Bond Classes Hierarchy	112
4.5	The Document Architecture	112
4.6	Editing Models.	118
4.6.1	The Editing Box	118
4.6.2	Developing Bond Graph Models.	121
4.6.3	Developing Block Diagram Models.	126
4.6.4	Modelling Discrete-Time Processes	129
4.7	Generating Electrical and Mechanical Schemas.	131
4.7.1	Developing Electrical Circuits	131
4.7.2	Developing Mechanical Circuits	134
4.8	Editing Elementary Components Constitutive Relations.	135
4.8.1	Component Port Dialogues.	135
4.8.2	Defining the Parameters.	138

4.9	Library Operations	141
4.9.1	Library Projects	142
4.9.2	Library Components	143
4.10	Important Operations at the Document Level	146
4.10.1	Open, Close and Save Commands.	147
4.10.2	Page Layout and Print Commands	148
4.10.3	The Delete, Copy, Cut, and Insert Operations.	149
4.11	Inter-process Communications	151
	References	155
5	Generation of the Model Equations and Their Solution	157
5.1	Introduction	157
5.2	General Forms of the Model Equations	158
5.2.1	Generating the System Variables.	158
5.2.2	Generation of the Equations	162
5.2.3	The Characteristics of the Model	166
5.3	Numerical Solution Using BDF Methods.	173
5.3.1	The Implementation of the BDF Method	173
5.3.2	The Generation of the Partial Derivative Matrix	177
5.3.3	The Error Control Strategy.	177
5.4	Decompiling the Model Equations	180
5.5	The Problem of Starting Values	182
5.6	The Treatment of Discontinuities	185
5.7	A Stack Based Approach to Function Evaluation	186
	References	189

Part II Applications

6	Mechanical Systems	193
6.1	Introduction	193
6.2	The Body Spring Damper Problem	194
6.2.1	The Problem	194
6.2.2	The Bond Graph Model.	194
6.2.3	Analysis of the System Behaviour by Simulation	208
6.3	Effect of Dry Friction	222
6.3.1	The Model of Dry Friction.	222
6.3.2	Free Vibration of a Body with Dry Friction	229
6.3.3	Stick-Slip Motion	231
6.3.4	The Stick-Slip Oscillator	234
6.4	Bouncing Ball Problems	237
6.4.1	Simple Model of Impact	237
6.4.2	A Ball Bouncing on a Table.	241
6.4.3	A Ball Bouncing on a Vibrating Table	243
6.5	The Pendulum Problem.	245
	References	251

7	Electrical Systems	253
7.1	Introduction	253
7.2	Electrical Circuits	254
7.2.1	The Problem	254
7.2.2	The Bond Graph Model	255
7.2.3	Analysis of the System Behaviour by Simulation	263
7.3	Models of Circuit Elements	266
7.3.1	Resistors	266
7.3.2	Capacitor	267
7.3.3	Inductors	269
7.3.4	Sources	272
7.3.5	Switches	279
7.4	Modelling Semiconductor Components	282
7.4.1	Diodes	283
7.4.2	Transistors	298
7.4.3	Operational Amplifiers	317
7.5	Electromagnetic Systems	324
7.5.1	Electromagnetic Actuator Problem	324
7.5.2	System Bond Graph Model	325
7.5.3	Electromagnetic Flux and Force Expressions	326
7.5.4	Magnetic Actuator Component Model	328
7.5.5	Simulation of Magnetic Actuator Behaviour	330
	References	332
8	Control Systems	333
8.1	Introduction	333
8.2	A Simple Control System	334
8.3	PID Control System Modelling	343
8.4	Permanent Magnet DC Servo System	347
	References	355
9	Multibody Dynamics	357
9.1	Introduction	357
9.2	Modelling of Rigid Multibody Systems in Plane	358
9.2.1	The Component Model of a Rigid Body in Planar Motion	358
9.2.2	Joints	363
9.2.3	Modelling and Simulation of a Planar Mechanism	368
9.3	Andrews' Squeezer Mechanism	373
9.4	Engine Torsional Vibrations	383
9.5	Motion of Constrained Rigid Bodies in Space	391
9.5.1	Basic Kinematics	391
9.5.2	Bond Graph Representation of a Body Moving in Space	396

9.5.3	Rigid Body Dynamics	401
9.5.4	Modelling of Body Interconnections in Space.	404
9.6	Dynamics of Puma 560 Robot	413
9.6.1	Problem Formulation.	413
9.6.2	Model of the Robot.	419
9.6.3	Simulation of PUMA 560	428
9.7	3D Visualization of Robots	434
9.7.1	Concept of 3D Visualization	434
9.7.2	Generating 3D Virtual Scene	436
9.7.3	Visualization of Robot Dynamics	445
	References	447
10	Continuous Systems	449
10.1	Introduction	449
10.2	Spatial Discretisation of Continuous Systems	450
10.3	Model of Electric Transmission Line.	452
10.4	Bond Graph Model of a Beam	459
10.5	A Packaging System Analysis	465
10.5.1	Description of the Problem.	465
10.5.2	Bond Graph Model Development	466
10.5.3	Evaluation of Vibration Test Characteristics	474
10.6	Coriolis Mass Flowmeters	477
10.6.1	Problem Statement	477
10.6.2	Principle of Operations	478
10.6.3	Dynamics of Curved CMF Tubes	480
10.6.4	Bond Graph Model of CMF Transducer	490
10.6.5	Control of CMF Transducer	494
10.6.6	Simulation of CMF Control Loop	501
	References	503
	Appendix	505
	Index	507