

Contents

Nomenclature	v
Kurzfassung	1
Abstract	2
1 Introduction	5
1.1 Motivation	5
1.2 Overview	7
1.3 State of research	9
1.4 Outline	11
2 Basic principles of continuum mechanics	15
2.1 Reference configuration and current configuration	15
2.2 Deformation and strains	17
2.2.1 Deformation gradient	17
2.2.2 Displacement gradient	19
2.2.3 Polar decomposition	19
2.2.4 Strain tensors	19
2.3 Stress	20
2.3.1 Traction vector	20
2.3.2 Stress tensors	21
2.4 Conservation laws	22
2.4.1 Conservation of mass	22
2.4.2 Conservation of linear and angular momentum	23
2.4.3 Conservation of energy	24
2.4.4 Entropy inequality	25
2.5 Constitutive laws	25
2.5.1 Helmholtz free energy	26
2.5.2 J_2 -plasticity for small strains	28
2.6 Variational principles and linearization	30
2.6.1 Variational principle	30

2.6.2	Linearization	33
2.6.3	Mixed field formulations	34
3	Nonlinear shell theory	37
3.1	Shell kinematics	38
3.1.1	Green-Lagrange strains and shell strains	41
3.2	Stress and stress resultants	43
3.3	Equilibrium conditions	44
3.4	Mixed field formulation	46
4	Finite element formulation	49
4.1	Approximation of geometry	49
4.2	Interpolation and variation of Green-Lagrangian strains	51
4.3	Second variation of the functional	55
4.4	Interpolation of stress resultants and shell strains	57
4.5	Linearized variational functional	59
5	The coupled global-local shell model	61
5.1	Extension to the local model	61
5.2	Local assembly of the coupled system	63
5.3	Boundary conditions for the RVE	67
5.4	Simultaneous iteration	69
6	Numerical modeling of sandwich structures	71
6.1	Parameter terminology	72
6.2	Unidirectionally stiffened sandwich panel	72
6.2.1	Validation of RVE material matrix	72
6.2.2	Axially stiffened sandwich beam	78
6.2.3	Geometrically nonlinear deformation behavior	83
6.3	Bidirectionally stiffened sandwich cell	85
6.3.1	Validation of RVE material matrix	85
6.3.2	Linear deformation behavior	88
6.3.3	Comparison of stress resultants	91
6.3.4	Geometrically nonlinear deformation behavior	94
6.3.5	Physically nonlinear deformation behavior	97
6.4	Hexagonal honeycomb sandwich cell	108
6.4.1	RVE material matrix	111
6.4.2	Honeycomb sandwich plate	114

7	Mesh generation	119
7.1	Automated mesh generation for FEAP using Python scripts	120
7.2	Conversion of Abaqus meshes using inp2feap	121
8	Parallelization and effective data transfer in a finite element program	125
8.1	Parallel computer architectures	126
8.1.1	Increase in computational power due to more processing cores . . .	127
8.1.2	Memory-bound applications	128
8.1.3	Memory topologies in parallel machines	129
8.1.4	Potential benefits and drawbacks of hardware accelerators	129
8.2	Parallel programming issues and pitfalls	130
8.2.1	Race conditions	130
8.2.2	Deadlocks	131
8.2.3	Determinism of floating point arithmetics	132
8.2.4	Address locality and inter-process communication	132
8.3	FEAP shared memory extension	133
8.4	Shared memory performance	135
9	Conclusion and future perspectives	139
	Bibliography	144