

Contents

Application of Neural Networks in High Assurance Systems: A Survey	1
Johann Schumann, Pramod Gupta, Yan Liu	
1 Introduction	1
2 Application Domains	3
2.1 Aircraft Control	4
2.2 Automotive	4
2.3 Power Systems	5
2.4 Medical Systems	6
2.5 Other Applications	7
3 Toward V&V of NNs in High Assurance Systems	8
3.1 V&V of Software Systems	8
3.2 V&V Issues and Gaps for NN-Based Applications	10
3.3 V&V Approaches for Neural Networks	11
4 Conclusions	15
References	16
Robust Adaptive Control Revisited: Semi-global Boundedness and Margins	21
Anuradha M. Annaswamy, Jinho Jang, Eugene Lavretsky	
1 Introduction	21
2 Problem Statement	22
3 Adaptive Controller	24
3.1 Reference Model	24
3.2 Adaptive Controller Design	24
3.3 Stability Analysis	25
4 Delay Margins	25
4.1 (1, 1) Padé Approximation ($\eta = \Delta_1(s)u$)	26
4.2 (2, 2) Padé Approximation ($\eta = \Delta_2(s)u$)	30

5	Nonlinearity Margins	31
5.1	Interpretation of Theorem 3	34
5.2	Numerical Model: Hypersonic Vehicle	34
5.3	Relation between $e(t_0)$, $\epsilon(x_p)$, and N	36
	References	38
A	Appendix	39
	Network Complexity Analysis of Multilayer Feedforward Artificial Neural Networks	41
	Xiao-Hua Yu	
1	Introduction	41
2	Pruning Algorithms	44
3	Computer Simulation Results	50
4	Summary	53
	References	53
	Design and Flight Test of an Intelligent Flight Control System	57
	Tim Smith, Jim Barhorst, James M. Urnes, Sr.	
1	Introduction	57
2	IFCS Program	58
3	IFCS Experiment	59
4	Controller Architecture	61
5	Requirements Validation	63
5.1	System Stability	64
5.2	Aeroservoelastic Margin	64
5.3	Handling Qualities	66
5.4	Nonlinear Systems Requirements Validation	67
6	Flight Controls Software and System Verification	70
7	Flight Test	74
8	Conclusions	75
	References	76
	Stability, Convergence, and Verification and Validation Challenges of Neural Net Adaptive Flight Control	77
	Nhan T. Nguyen, Stephen A. Jacklin	
1	Introduction	77
2	Convergence and Stability of Neural Net Direct Adaptive Flight Control	79
2.1	Direct Adaptive Control Approach	80
2.2	Stability and Convergence	82
2.3	Unmodeled Dynamics	90
3	Potential Improvements	93

3.1	Direct Adaptive Control with Recursive Least Squares	93
3.2	Hybrid Direct-Indirect Adaptive Control with Recursive Least-Squares	96
4	Verification and Validation Challenges for Adaptive Systems	99
4.1	Simulation of Adaptive Control Systems	99
4.2	Approach for Adaptive System V&V	101
5	Future Research	103
5.1	Adaptive Control	103
5.2	Verification and Validation	105
6	Conclusions	107
References		107
Dynamic Allocation in Neural Networks for Adaptive Controllers		111
Sampath Yerramalla, Edgar Fuller, Bojan Cukic		
1	Introduction	111
1.1	Paper Overview	113
2	Dynamic Allocation in Neural Networks	113
2.1	Dynamic Cell Structures	114
2.2	Components of DCS Neural Network	114
2.3	DCS Algorithm	117
3	Robustness Analysis of Dynamic Allocation	119
3.1	Node Insertion	119
3.2	Analysis for UC1 (Undesirable Condition 1)	120
3.3	Analysis for UC2 (Undesirable Condition 2)	122
4	Data-Driven Dynamic Allocation Algorithm	127
5	Case Study	131
6	Conclusion	138
References		138
Immune Systems Inspired Approach to Anomaly Detection, Fault Localization and Diagnosis in Automotive Engines		141
Dragan Djurdjanovic, Jianbo Liu, Kenneth A. Marko, Jun Ni		
1	Introduction	141
2	Research Issues in Immune Systems Engineering	143
2.1	Anomaly Detection and Fault Localization	146
2.2	Fault Diagnosis	148
2.3	Automatic Control System Reconfiguration	149
3	Anomaly Detection, Fault Isolation and Diagnosis in an Automotive Electronic Throttle System	150
3.1	Anomaly Detection and Fault Isolation	150
3.2	Fault Diagnosis	152
3.3	Fever-Like Behavior in the Presence of an Unknown Fault	153

4	Anomaly Detection and Fault Isolation in Automotive Crankshaft Dynamics	156
5	Conclusions and Future Work	160
References		161
Pitch-Depth Control of Submarine Operating in Shallow Water via Neuro-adaptive Approach		
Y.D. Song, Liguu Weng, Medorian D. Gheorghiu		165
1	Introduction	165
2	Dynamics	166
2.1	Nonlinear Model	167
2.2	Fault Dynamics	168
3	Control Design	169
3.1	Nonlinear Model	169
3.2	Stability Analysis	171
4	Simulation Results	172
5	Conclusions	177
References		177
Stick-Slip Friction Compensation Using a General Purpose Neuro-adaptive Controller with Guaranteed Stability		
Ali Reza Mehrabian, Mohammad Bagher Menhaj		179
1	Introduction	179
2	The Neural-Network-Based Control Strategy	182
2.1	Indirect Adaptive Neuro-Controller	182
2.2	Neural Network Scheme	183
2.3	Control Oriented On-Line Identification Method	183
2.4	Mathematical Description of the Control Scheme	184
2.5	Training Multilayer Neural Network (MLP)	186
2.6	Back-Propagation through the Model	186
3	Stability Analysis	187
4	Implementing the Proposed Adaptive-Neuro Control Method ...	188
4.1	NN Identifier Block	188
4.2	NN Controller Block	191
4.3	Controller Error Sensitivity Feedback Block	191
5	Simulation Studies	192
5.1	Example 1: A Non-linear System with a Second-Order Difference Equation and Variable Reference Model	192
5.2	Example 2: A Non-linear Plant Subjected to Uncertainty	194
6	Stick-Slip Friction Compensation Using the Introduced Neuro-Control Algorithm	195
6.1	Problem Statement	195

6.2	Simulation Results	196
7	Conclusions	200
References		201
Modeling of Crude Oil Blending via Discrete-Time Neural Networks ...		205
Xiaoou Li, Wen Yu		
1	Introduction	205
2	Crude Oil Blending	206
3	Modeling of Crude Oil Blending via Discrete-Time Neural Networks	208
4	Application Study	213
5	Conclusion	218
References		219
Adaptive Self-Tuning Wavelet Neural Network Controller for a Proton Exchange Membrane Fuel Cell		221
M. Sedighzadeh, A. Rezazadeh		
1	Introduction	222
2	PEMFC System Model	223
3	Wavelet Neural Network and Identification Algorithm	226
	3.1 Wavelet Neural Network	226
	3.2 System Model Identification	228
4	Proposed Controller Design	230
	4.1 Neural Network Controller Based on Wavelet	230
	4.2 PID Neural Network Controller Based on Wavelets	230
5	Simulation Results	232
	5.1 Identification of PEMFC	232
	5.2 Control of PEMFC without Noise	233
	5.3 Control of PEMFC with Input Noise	236
	5.4 Control of PEMFC with Output Noise Problem	240
6	Conclusions	244
References		244