

# Contents

<b>1</b>	<b>Variable Thrust Angle Constant Thrust Collision Avoidance Maneuver</b> . . . . .	<b>1</b>
	Yongqiang Qi and Yong Ma	
<b>2</b>	<b>Robust Control for Constant Thrust Rendezvous</b> . . . . .	<b>9</b>
	Yongqiang Qi and Minghui Ou	
<b>3</b>	<b>Dissipativity Analysis and Synthesis of Singular Systems via Delta Operator Method</b> . . . . .	<b>17</b>
	Chun-ming Qi, Xin-zhuang Dong and Lin Liu	
<b>4</b>	<b>Intelligent Welding Robot Path Planning</b> . . . . .	<b>25</b>
	Xue Wu Wang, Ying Pan Shi, Rui Yu and Xing Sheng Gu	
<b>5</b>	<b>The Design and Implementation of a Somatosensory Tactile Actuator and the Dynamic Calibration System for Its Output Frequencies</b> . . . . .	<b>33</b>
	Hui Wang, Bowei Li, Aiguo Song and Quanjun Song	
<b>6</b>	<b>A Visual Feedback Control Framework Oriented to Lung Branching Pattern Formation Simulation</b> . . . . .	<b>43</b>
	Hui Xu, Mingzhu Sun, Jianda Han and Xin Zhao	
<b>7</b>	<b>Path Following and Obstacle Avoidance Control Based on Different Fuzzy Grains</b> . . . . .	<b>55</b>
	Yifei Kong, Chaoyi Chen, Yuequan Yang and Zhiqiang Cao	
<b>8</b>	<b>Artificial Immune System Used in Rotating Machinery Fault Diagnosis</b> . . . . .	<b>65</b>
	Linhui Zhao, Lihua Zhou, Yaping Dai and Zhongjian Dai	

<b>9</b>	<b>The Application of a Parameter Adaptive Iterative Learning Control on Three-Axis Angular Vibration Turntable . . . . .</b>	<b>75</b>
	Ruoxuan Luan and Zhen Chen	
<b>10</b>	<b>Position Control of Interior Permanent Synchronous Motor Based on Improved Shakeless Fuzzy Controller. . . . .</b>	<b>83</b>
	Mingling Shao, Haisheng Yu, Zihan Wang, Hongchao Xie and Shuai Zhao	
<b>11</b>	<b>Modeling and Stability Analysis for Networked Hierarchical Control of Islanded Microgrid. . . . .</b>	<b>91</b>
	Lizhen Wu, Xusheng Yang, Hu Zhou and Xiaohong Hao	
<b>12</b>	<b>Variable Thrust Angle Constant Thrust Rendezvous . . . . .</b>	<b>101</b>
	Yongqiang Qi and Ding Lv	
<b>13</b>	<b>Robust Control Method Applied in Constant Thrust Rendezvous Under Thrust Failure. . . . .</b>	<b>109</b>
	Yongqiang Qi	
<b>14</b>	<b>Stabilization of Underactuated Surface Vessel Based on Backstepping Control Method . . . . .</b>	<b>117</b>
	Chuang Zhang and Chen Guo	
<b>15</b>	<b>BMI Optimization Based on Improved Path-Following Method in Control . . . . .</b>	<b>127</b>
	Jian Chen and Chong Lin	
<b>16</b>	<b>H-Infinity Quantized Feedback Control for Networked Control Systems with Periodic Scheduling Protocol . . . . .</b>	<b>135</b>
	Chuan Zhou, Hui Lu and Ronghao Wang	
<b>17</b>	<b>Wind Speed Estimation and Station-Keeping Control for Stratospheric Airships with Extended Kalman Filter. . . . .</b>	<b>145</b>
	Shaoping Shen, Ling Liu, Bomin Huang, Xianwu Lin, Weiyao Lan and Huiyu Jin	
<b>18</b>	<b>Integral Sliding Mode Control for Vehicle-Mounted Gyro-Stabilized Platform Based on Extended State Observer . . . .</b>	<b>159</b>
	Haoze Sun, Tianqing Chang, Junwei Chen, Lei Zhang and Kuifeng Su	

<b>19 Robust <math>H_\infty</math> Fuzzy Dynamic Output Feedback Control of Nonlinear NCS and Its Application . . . . .</b>	<b>169</b>
Qingfeng Wang and Hongbo Wang	
<b>20 Study on the Control System of the Wheel Hanging Workbench . . . . .</b>	<b>181</b>
Chaokun Ma, Naijian Chen, Changchun Li and Longtao Liu	
<b>21 An Overview of Dynamic Equilibrium State Theory. . . . .</b>	<b>193</b>
Linjie Xin, Qinglin Wang and Yuan Li	
<b>22 RBFNN-Based Path Following Adaptive Control for Underactuated Surface Vessels. . . . .</b>	<b>203</b>
Wei Meng and Chen Guo	
<b>23 Sliding Mode Tracking and Input Shaped Vibration Control of Flexible Hypersonic Vehicles . . . . .</b>	<b>213</b>
Xiaoyun Wang and Yingmin Jia	
<b>24 An Application of Artificial Neural Networks in Crane Operation Status Monitoring. . . . .</b>	<b>223</b>
Jan-Li Yu, Rui-Fang Zhou, Man-Xiang Miao and Hong-Qi Huang	
<b>25 Adaptive Fuzzy Dynamic Surface Control for Induction Motors via Backstepping . . . . .</b>	<b>233</b>
Fatao Shi, Yumei Ma, Jinfei Yu, Jinpeng Yu and Ziyang Qu	
<b>26 Fault Tolerant Control with TSM for Spacecraft Formation Flying . . . . .</b>	<b>243</b>
Xiaoyu Han and Yingmin Jia	
<b>27 Position Control of Induction Motors via Adaptive Fuzzy Backstepping with Input Saturation. . . . .</b>	<b>255</b>
Wei Li, Yumei Ma, Jinfei Yu, Jinpeng Yu and Jiapeng Liu	
<b>28 A Fault Detection and Isolation Method Based on R-Fast ICA and K-Fisher for Roller Bearings on the Urban Rail Vehicles . . . . .</b>	<b>265</b>
Linlin Kou, Yong Qin, Xiaoqin Cheng and Zhenyu Zhang	
<b>29 Finite-Time Synergetic Control of Mechanical System Based on Model-Free Friction Compensation . . . . .</b>	<b>275</b>
Shuangpo Zhai, Qiang Chen and Xiaoqing Tang	

<b>30</b>	<b>Feedback Gain Scheduling Controller Design for Networked Control Systems with Accurate Measurement of QoS . . . . .</b>	<b>285</b>
	Hong Yao, Jian-Qiu Deng, Cui Hao, Zeng-Qi Sun and Xin Lu	
<b>31</b>	<b>Adaptive Fuzzy Control Based on Variable Universe for Ship Course . . . . .</b>	<b>299</b>
	Yuchao Wang, Huixuan Fu and Sheng Liu	
<b>32</b>	<b>Alignment of MEMS in Civilian Vehicle Navigation . . . . .</b>	<b>309</b>
	Yun Wang, Chun Yang and Lei Zhang	
<b>33</b>	<b>Simulation Study of General Cargo Yard Layout . . . . .</b>	<b>317</b>
	Lu Wu, Yu Zhang, Dongdong Wang and Zhixiong Liu	
<b>34</b>	<b>Stowage Plan Research Based on Hierarchical Decomposition. . . . .</b>	<b>331</b>
	Dongdong Wang, Yu Zhang, Lu Wu and Guangwei Tian	
<b>35</b>	<b>Decentralized Robust Predictive Control for Convex Polyhedral Uncertain Large-Scale Systems. . . . .</b>	<b>343</b>
	Wenwen Guan, Chaoyong Jin and Liping Xie	
<b>36</b>	<b>Research on Natural Gas Pipeline Leak Detection Algorithm and Simulation . . . . .</b>	<b>355</b>
	Daiyong Zhou	
<b>37</b>	<b><math>H_\infty</math> Filtering for Network-Based Systems with Time-Varying Delay . . . . .</b>	<b>363</b>
	Duanjin Zhang and Xiaojing Jie	
<b>38</b>	<b>A Comparative Study of Pricing Control Algorithms in Deregulated Electricity Market . . . . .</b>	<b>373</b>
	Zhi-Yu Xu, Wei-Hui Shao, Hai-Ni Qu, Ke Sun and Wei-Sheng Xu	
<b>39</b>	<b>Adaptive Output Feedback Control of Nonlinear Systems with States and Input Unmodeled Dynamics . . . . .</b>	<b>383</b>
	Xiaonan Xia, Tianping Zhang and Qin Wang	
<b>40</b>	<b>Control of Powered Knee Joint Prosthesis Based on Finite-State Machine . . . . .</b>	<b>395</b>
	Guoxing Chen, Zuojun Liu, Lingling Chen and Peng Yang	

41    **Robust PI-Type Position Controller Design for Permanent Magnet Synchronous Motor Using LMI Techniques. . . . .**    405  
Xiaokang Sun, Yang Yi, Songyin Cao, Heqing Liu and Tianping Zhang

42    **Reviews to the Research on Building Electrical Intelligent Fault Self-diagnosis. . . . .**    413  
Jiajun Wang and Yahui Wang

43    **Output Feedback for Networked Control Systems with Time-Delay and Data Packet Dropout . . . . .**    423  
Wang Yan-Feng, Li Zu-Xin, Chen Hui-Ying and Qian Yi

44    **Design of an Improved Variable Universe Fuzzy Control System and Its Stability Analysis. . . . .**    433  
Weihua Huang and Haiyan Long

45    **Experimental Study on Adaptive Iterative Control for Lower Limb Prostheses . . . . .**    443  
Yu-liang Ma, Xiao-hui Ding, Ming Meng and Qing-shan She

46    **Dynamic Surface Control for a Class of Nonlinear Systems in the Presence of Input Saturation . . . . .**    455  
Cao Pi and Jinkun Liu

47    **Sliding-Mode Control of a Class of Nonlinear Systems in the Presence of Input Saturation . . . . .**    465  
Jinkun Liu and Cao Pi

48    **Fault Diagnosis with Adaptive Projection Algorithms for Complex Non-Gaussian Stochastic Distribution Systems . . . . .**    475  
Yangfei Ye, Yang Yi, Xiaokang Sun and Tianping Zhang

49    **Multimode Anomaly Detection Under the Multiscale Framework . . . . .**    483  
Funa Zhou, Yu Zhang, Xiaoliang Feng, Chenglin Wen and Juan Wang

50    **Mixed  $H_2/H_\infty$  Robust Controller with Degree Constraint in Angular Metric. . . . .**    493  
Bin Liu, Yangyang Cui and Jiuqiang Sun

<b>51</b>	<b>ADRC Based Attitude Control of a Quad-rotor Robot . . . . .</b>	<b>503</b>
	Yi Li, Zengqiang Chen, Mingwei Sun, Zhongxin Liu and Qing Zhang	
<b>52</b>	<b>Design and Implementation of a PMSM Rotor Position Detecting System with High Speed and High Precision . . . . .</b>	<b>513</b>
	Bo Zhu, Huailin Zhao, Jihong Zhu and Yang He	
<b>53</b>	<b>Analysis and Design of Disturbance Observer for Piezoelectric Hysteresis Nonlinear System. . . . .</b>	<b>521</b>
	Hefei Sun and Zhen Zhang	
<b>54</b>	<b>PID Tuning for LOS Stabilization System Controller Based on BBO Algorithm . . . . .</b>	<b>533</b>
	Kuifeng Su, Tianqing Chang, Bin Zhu and Bin Han	
<b>55</b>	<b>Low Altitude Photogrammetry Positioning Technology in Evaluation of GNSS Dynamic Positioning Accuracy . . . . .</b>	<b>541</b>
	Dian-Wei Cong and Qi-Feng Xu	
<b>56</b>	<b>Discrete-Time Integral Sliding Mode Fault-Tolerant Control with Uncertainties. . . . .</b>	<b>551</b>
	Duan Wenjie, Wang Dayi and Liu Chengrui	
<b>57</b>	<b>Parametric Design of a Descriptor Functional Observer for Standard Linear Systems. . . . .</b>	<b>567</b>
	Guosheng Wang, Feng Guo and Bing Liang	
<b>58</b>	<b>Stability Analysis of FDCM-Based Controller for Hypersonic Vehicles . . . . .</b>	<b>577</b>
	Xiong Luo and Ruixin Li	