Contents

L			On
	1.1		istory of INS/CNS/GNSS Navigation
	1.2		urrent Status of INS/CNS/GNSS Navigation Development
		1.2.1	INS/GNSS Navigation
		1.2.2	INS/CNS Navigation
		1.2.3	INS/CNS/GNSS Navigation
	Refe	erences	
2	Prin	ciple o	f INS/CNS/GNSS Navigation System
	2.1		uction
	2.2	2 Coordinate Frames and Earth Reference Model Commonly Used	
		Navig	ation
		2.2.1	The Coordinate Frames Used in Navigation
		2.2.2	The Conversion of Coordinate Systems
		2.2.3	Earth Reference Model
	2.3	Inertia	al Navigation System
		2.3.1	Work Principle of Inertial Navigation System
		2.3.2	SINS System Error Equation and Error Propagation
			Characteristics
	2.4	2.4 Satellite Navigation System	
		2.4.1	Operating Principle of Satellite Navigation System
		2.4.2	Analysis of Error Characteristics for Satellite Navigation
			System
	2.5	Celest	tial Navigation System
		2.5.1	Autonomous Celestial Positioning Principle
		2.5.2	Celestial Attitude Determination Principle
		2.5.3	Star Sensor in CNS and Analysis of Its Error Characteristics
	2.6	Chapt	er Conclusion
	Refe	erences	

xii Contents

3	Filte	ers in Navigation System		53
	3.1	Introduction		53
	3.2	Kalman Filter		54
	3.3	Extended Kalman Filter		56
		3.3.1 Mathematical Descriptio	n of Stochastic Nonlinear System	56
		3.3.2 Discrete Extended Kalma	an Filter	57
	3.4	Unscented Kalman Filter		59
	3.5	Particle Filter		61
	3.6			64
	3.7			65
	3.8			68
			lter	68
				69
	3.9			70
		•		71
4	Erre	or Modeling, Calibration, and	Compensation of Inertial	
	Mea	surement Unit (IMU)		75
	4.1	Introduction		75
	4.2	Error Modeling and Compensati	on of Inertial Sensors	76
		4.2.1 Error Model of Gyroscop	oes	76
		4.2.2 Scale Factor Error Mode	ling of Gyroscope	78
		4.2.3 Temperature Error Mode	ling of Gyroscope	85
	4.3	Design, Error Calibration, and	Compensation of Inertial	
		Measurement Units	- 	90
		4.3.1 Design of Inertial Measu	rement Units	90
		4.3.2 The Optimization Six-Po	sition Hybrid Calibration for SINS.	104
		<u>-</u>	ethod for RLG IMU Using a	
		•	Filter Approach	108
			eling of IMU Based on Neural	
		Network		117
	4.4		al Algorithm	123
		4.4.1 Error Analysis and Gyro	Biases Calibration of Analytic	
		Coarse Alignment for Ai	rborne POS	124
		_	and Evaluation Criteria for	
			tion Algorithm	131
			sample Rotating Vector Attitude	
				132
	4.5	Chapter Conclusion		141
	Refe	•		142
5		Map Processing Algorithm of		
		9		145
	5.1			145
	5.2	Star Map Preprocessing Method	for Star Sensors	145

Contents xiii

146 148 150 152 158 159 160 161 167 170 171 172 176 178 181 181 185 185 186 on 186 187 m 189
148 150 152 158 159 160 161 167 169 170 171 172 176 178 181 181 181 185 186 on 186 187
150 152 158 159 160 161 167 169 170 171 172 176 178 181 181 181 185 186 on 186 187
152 158 159 160 161 167 169 170 171 172 176 178 181 181 181 185 186 on 186 187
158 159 160 161 167 169 170 171 172 178 181 181 181 185 186 on 186 187
159 160 161 167 169 170 171 172 176 178 181 181 185 185 186 on 186 187
160 161 167 169 170 171 172 176 178 181 181 185 185 186 on 186 187
161 167 169 170 171 172 176 178 181 181 185 185 186 on 186 187
167 170 171 172 176 178 181 181 185 185 186 on 186 187
169 170 171 . 172 176 178 181 181 185 185 186 on 186 187
170 171 172 176 178 181 181 185 185 186 on 186 187
. 171 . 172 . 176 . 178 . 181 . 181 . 185 . 185 . 186 on 186 . 187
. 171 . 172 . 176 . 178 . 181 . 181 . 185 . 185 . 186 on 186 . 187
. 172 176 178 181 181 185 185 186 on 186 187
176 178 181 181 181 185 185 186 on 186 187
176 178 181 181 181 185 185 186 on 186 187
178 181 181 181 185 185 186 on 186 187
181 181 185 185 186 on 186 187
181 185 185 186 on 186 187
181 185 185 186 on 186 187
185 185 186 on 186 187
185 186 on 186 187
185 186 on 186 187
186 on 186 187
on 186 187
187
111 109
. 190
. 190
102
. 193
199
200
. 200
. 203
. 209
n 214
n 214

Contents

7	INS/CNS Integrated Navigation Method			237
	7.1		luction	237
	7.2	Basic	Principle of Inertial/Celestial Integrated Navigation	238
		7.2.1	Operating Mode of the Inertial/Celestial Integrated	
			Navigation System	238
		7.2.2	Combination Mode of Inertial/Celestial Integrated	
			Navigation System	240
		7.2.3	Principle of Inertial Component Error Correction Based on	
			Celestial Measurement Information	241
	7.3	Mode	ling Method of Inertial/Celestial Integrated Navigation	
		Syster	m	242
		7.3.1	State Equation of Inertial/Celestial Integrated Navigation	
			System	243
		7.3.2	Measurement Equation of Inertial/Celestial Integrated	
			Navigation System	245
	7.4	New I	Inertial/Celestial Integrated Navigation Method of Ballistic	
		Missil	le	245
		7.4.1	Principle for Initial Position Error Correction of Missile	
			Launching Point Based on Celestial Measurement	
			Information	246
		7.4.2	Inertial/Celestial Integrated Navigation Method of Ballistic	
			Missile Based on UKF	246
	7.5	Inertia	al/Celestial Integrated Navigation Method of Lunar Vehicle	250
		7.5.1	Strapdown Inertial Navigation Method of Lunar Vehicle	251
		7.5.2	A Lunar Inertial/Celestial Integrated Navigation Method	
			Based on UPF	252
	7.6	Inertia	al/Celestial Integrated Attitude Determination Method of	
		Satelli	ite	257
		7.6.1	Satellite Attitude Determination System Equation	257
		7.6.2	An Inertia/Celestial Integrated Attitude Determination	
			Method of Piecewise Information Fusion Based on EKF	259
		7.6.3	Method of Minimum Parameter Attitude Matrix Estimation	
			of Satellite Based on UKF	263
		7.6.4	Interlaced Optimal-REQUEST and Unscented Kalman	
			Filtering for Attitude Determination	269
	7.7	Chapt	ter Conclusion	275
	Refe	erences		276
8	INS	/CNS/0	GNSS Integrated Navigation Method	279
	8.1		luction	279
	8.2		iple of INS/CNS/GNSS Integrated Navigation	280
		8.2.1	Basic Principle of INS/CNS/GNSS Integrated Navigation	280
		8.2.2	Combination Mode of INS/CNS/GNSS	
			Integrated Navigation	280
		8.2.3	Modeling of INS/CNS/GNSS Integrated Navigation System	285

Contents xv

	8.3		S/GNSS Integrated Navigation Method Based on dUKF	287
	8.4		d Filtering INS/CNS/GNSS Integrated Navigation	201
	0.4		Based on the Optimized Information Distribution	
			based on the Optimized Information Distribution	291
			Federated Filtering Equation and Information	2)1
			Distribution Process	291
			Federated Filtering INS/CNS/GNSS Integrated	291
			Navigation Method Based On Information Distribution	
			Factor Optimization	293
			Research on FKF Method Based on an Improved	29.
			Genetic Algorithm for INS/CNS/GNSS Integrated	
			Navigation System	294
	8.5		Conclusion	304
		-	Conclusion	304
	Kerei	ciices		50-
9			-Time Ability of INS/CNS/GNSS Integrated	
		9	thod	307
	9.1		tion	307
	9.2		e Constant System (PWCS) Observability Analysis	
			nd Method	308
			Observability Analysis Theory of the PWCS	308
			An Improved System State Degree of Observability	
			Analysis Method Based on Singular Value	
			Decomposition	313
	9.3		onality Reduction Filter Design of INS/CNS Integrated	
		Navigation	on System Based on the Improved Degree of	
			pility Analysis	315
	9.4	Dimension	onality Reduction Filter Design of INS/GNSS Integrated	
		Navigation	on System Based on the Improved Degree of	
		Observat	bility Analysis	318
	9.5	Federate	d Filter Design of the INS/CNS/GNSS Integrated	
		Navigation	on System Based on Dimensionality Reduction Filtering	322
	9.6	Chapter	Conclusion	326
	Refe	rences		328
40			OL ALL TO A ANNO CONCIONO	
10			Simulation Technology of INS/CNS/GNSS	221
	Integ	grated Nav	vigation	331
	10.1		tion	33
	10.2		e and Composition of Semi-Physical Simulation System	224
			CNS/GNSS Integrated Navigation	332
			Principle of Semi-Physical Simulation System of	
			INS/CNS/GNSS Integrated Navigation	332
			Composition of Semi-Physical Simulation System of	
			INS/CNS/GNSS Integrated Navigation	334

xvi Contents

	10.3	Realization and Test of Semi-Physical Simulation System of	
		INS/CNS/GNSS Integrated Navigation	347
		10.3.1 Realization of Semi-physical Simulation System of	
		SINS/CNS/GNSS Integrated Navigation	350
		10.3.2 Experiments of Semi-physical Simulation System of	
		INS/CNS/GNSS Integrated Navigation	359
	10.4	Chapter Conclusion	361
	Refer	nces 3	361
11	Prost	ects of INS/CNS/GNSS Integrated Navigation Technology 3	363
_	11.1		363
	11.2	Development and Prospect of Integrated Navigation Technology .	
		11.2.1 Accurate Modeling Techniques of the INS/CNS/GNSS	363
		·	363
		11.2.2 Information Fusion of the INS/CNS/GNSS Navigation	
		<u> </u>	364
		11.2.3 INS/CNS/GNSS Navigation Method Based on	
		Advanced Control Theory	365
		11.2.4 Integrated Inertial/Celestial/Satellite Navigation	
		System Technology Based on Integration	368
		11.2.5 Applications of the Inertial/Celestial/Satellite	
		Navigation Technology	369
	11.3	Chapter Conclusion	370
	Refer	nces	370