

Contents

Part I: Robots and Sensor Networks Localization

Simultaneous Localization of Robots and Mapping of Wireless Sensor Nodes	3
<i>Andrea Zanella, Emanuele Menegatti</i>	
Robot-WSN Cooperation for Scalable Simultaneous Localization and Mapping	25
<i>Arturo Torres-González, José Ramiro Martínez-De Dios, Aníbal Ollero Baturone</i>	
Mobility-Assisted Localization Techniques in Wireless Sensor Networks: Issues, Challenges and Approaches	43
<i>Subir Halder, Amrita Ghosal</i>	

Part II: Cooperative Robots and Sensor Networks Applications

On the Cooperation between Mobile Robots and Wireless Sensor Networks	67
<i>Chia-Yen Shih, Jesús Capitán, Pedro José Marrón, Antidio Viguria, Francisco Alarcón, Marc Schwarzbach, Maximilian Laiacker, Konstantin Kondak, José Ramiro Martínez-De Dios, Aníbal Ollero Baturone</i>	
Collaborative Autonomous Surveys in Marine Environments Affected by Oil Spills	87
<i>Shayok Mukhopadhyay, Chuanfeng Wang, Mark Patterson, Michael Malisoff, Fumin Zhang</i>	
Human-Robot Mutual Trust in (Semi)autonomous Underwater Robots	115
<i>Yue Wang, Zhenwu Shi, Chuanfeng Wang, Fumin Zhang</i>	

Part III: System Engineering

Integrating Wireless Sensor Nodes in the Robot Operating System 141
Philipp M. Scholl, Martina Brachmann, Silvia Santini, Kristof Van Laerhoven

Mobile Sensing Platforms for Implementing Mobile Sensor Networks 159
Kemal Akkaya, Izzet Senturk, Shadi Jananasefat

Part IV: Mobility Management

Wireless Sensor Network Connectivity and Redundancy Repairing with Mobile Robots 185
Alberto de San Bernabé Clemente, José Ramiro Martínez-De Dios, Carolina Regoli, Aníbal Ollero Baturone

Fuzzy Logic Control for Mobility Support in Industrial Wireless Sensor Networks 205
Zinon Zinonos, Chrysostomos Chrysostomou, Vasos Vassiliou

Author Index 231