

Contents

List of Acronyms	9
Abstract	13
Kurzfassung	15
1 Introduction	17
1.1 Motivation	17
1.2 Statement of Problem - Thesis Objectives	19
1.3 Related Work	20
1.4 Research Methodology - Thesis Outline	22
2 Driver Assistance Systems	25
2.1 Active System for Crash Prevention	28
2.2 Passive System for Crashworthiness	29
2.3 Active System for Comfortable Vehicle Guidance	29
2.4 Passive System for Assistance by Additional Information	30
2.5 CAPS - Combined Active & Passive Safety from Bosch	33
3 Night Vision	37
3.1 Night Vision Enhancement Systems	38
3.2 System Setup and Functions of Bosch Night Vision System	40
3.3 Automotive HDR CMOS Camera from Bosch	42
4 Subjective Inspection of Stray Light	49
4.1 Error Sources and Effects causing Stray Light	50

4.2	Sensitivity of HDR Cameras to Stray Light	50
4.3	Test System and Testing Procedure	51
4.4	Visual Inspection based on Failure Catalogue	54
4.5	Disadvantages of Subjective Stray Light Inspection	55
4.6	Demand for Alternative Solution	57
5	Overview of Industrial Image Processing and Machine Learning	59
5.1	Industrial Image Processing	60
5.1.1	Framework in Digital Image Processing	60
5.1.2	Discussion of Useability of Conventional Industrial Image Processing for Objective Stray Light Inspection	63
5.2	Machine Learning	64
5.2.1	Mathematical Description and Framework of Classifiers	65
5.2.2	Decision Tree Learning: Random Forest	67
6	System Design for Objective Stray Light Inspection	73
6.1	Requirements	73
6.2	Framework	74
6.3	Implementation Details	78
7	Automation of Test Bench Hardware	81
7.1	Motor Unit	82
7.1.1	Technical Background	82
7.1.2	Relationship between Image and Motor Coordinates	82
7.1.3	<i>A Priori</i> Assessment of Accuracy, Precision and Test Coverage of Mo- torized Approach	86
7.2	Positioning of Motor Unit and Acquisition of Images	87
7.2.1	Computation of Light Spot Centre via Weighted Centroid Algorithm .	87
7.2.2	Overview of Basic Approaches for Positioning and Image Acquisition .	89
7.2.2.1	Exact positioning via feedback control and static image ac- quisition	89
7.2.2.2	Simple positioning without feedback control and static image acquisition	90
7.2.2.3	Dynamic positioning and image acquisition	90

7.2.3	Optimized Process Control for Enhancing Accuracy, Inspection Time and Test Coverage with respect to Different Spot Positions	91
7.2.3.1	Spot in image centre	92
7.2.3.2	Spot at control points inside the image field and above/below the image borders outside the image field	92
7.2.3.3	Spot inside and left/right of the image borders outside the image field	98
7.2.3.4	Discussion of influence of optical distortion on positioning accuracy	101
8	Preprocessing	105
8.1	Preparation of Data Set	105
8.1.1	Analysis of Grey Value Profiles in NV Images	105
8.1.2	Assembly of Training Set	110
8.1.3	Labelling Tool	112
8.2	Image Preprocessing	113
8.2.1	Noise Reduction by Gaussian Lowpass Filtering	113
8.2.2	Normalization	114
8.2.3	Transformation into Circle-Spoke Images by Polar Transformation and Bilinear Interpolation	115
9	Implementation of Feature Extraction	117
9.1	Statistical Features based on Grey Values	117
9.2	Feature Extraction Using the Example of Beam Artefacts	119
9.2.1	Image Preprocessing	120
9.2.2	Highpass Filtering for Flare Reduction at Image Borders	122
9.2.3	Binary Image Conversion by Thresholding	124
9.2.4	Morphological Operations	125
9.2.5	Hough Transform for Beam Detection in Binary Images	129

10 Classification	135
10.1 Evaluation Criteria for Classification Performance	135
10.1.1 Cross-Validation	136
10.1.2 Out-of-Bag Estimation Error	137
10.1.3 Predicted Artefact Probability, Receiver Operating Characteristic and Area under Curve	137
10.2 Results of Two-Class Classification via Cross-Validation	142
10.2.1 Evaluation of Out-of-Bag Estimation Error	143
10.2.2 Analysis of Predicted Artefact Probabilities and ROC Curves	145
11 Feature Selection	155
11.1 Significance Test of Differences between Features	157
11.2 Estimation of Variable Importance by means of Random Forests	162
11.3 Discussion of Results from Feature Selection	165
11.3.1 Significance Test	165
11.3.2 Variable Importance	172
11.3.3 Comparison between Significance Testing and VI Ranking	176
12 Concluding Remarks	181
12.1 Discussion	181
12.2 Future Work	189
A Adjustment Theory	193
B Image Enhancement	201
B.1 Fundamentals of Filtering	201
B.2 Noise Reduction	203
B.3 Edge Enhancement	205
C Bilinear Interpolation	207
D Overview of Classification Results	209

List of Figures	219
List of Tables	223
Bibliography	225
Acknowledgements	235
Curriculum Vitae	237