

Contents

Preface — V

Introduction — 1

1 Derivation of the Landau equation — 4

- 1.1 From Boltzmann equation to Landau equation — 4
- 1.2 Generalized Landau equation — 11
- 1.3 Transport cross-section of scattering in a weak central field — 13
- 1.4 From BBGKY hierarchy to Landau equation — 20
- 1.5 General comments on the Landau-type equations — 25
- Remarks on Chapter 1 — 27

2 Radially symmetric Landau equation and its models — 29

- 2.1 General properties of the Landau equation — 29
- 2.2 Radial solutions and related models — 32
- 2.3 Competition of diffusion and friction force — 34
- 2.4 Exactly solvable model — 38
- 2.5 Solutions of the model equation — 40
- 2.6 Models with variable diffusion coefficients — 43
- 2.7 Moment equations for the Landau equation — 47
- 2.8 Estimates of exponential moment $I_3(\lambda, t)$ and generalizations — 51
- 2.9 Asymptotic solutions and high-energy tails — 55
- Remarks on Chapter 2 — 59

3 Numerical methods for the Landau equation — 60

- 3.1 Landau equation in Fokker–Planck form — 60
- 3.2 Brief review of numerical methods — 60
- 3.3 The completely conservative difference schemes for the Landau–Fokker–Planck equation — 64
- 3.4 Example of the difference scheme for the generalized Landau equation — 66
- 3.5 Monte Carlo methods for LFPE — 73
- 3.6 General stochastic method — 76
- Remarks on Chapter 3 — 82

4 Applications of the Vlasov–Landau equation — 83

- 4.1 Vlasov–Landau equation for weakly interacting systems — 83
- 4.2 Vlasov–Poisson–Landau equation for plasma — 86
- 4.3 Asymptotic solutions of VPLE — 89
- 4.4 Behavior of $E^\varepsilon(x, t)$ for $\varepsilon \rightarrow 0$ — 91

4.5	Well-posedness of limiting kinetic equation —	93
4.6	Linearized Vlasov–Poisson equation —	96
4.7	More on vibrations of electric field —	104
4.8	The case of strong oscillations —	109
4.9	Numerical examples —	114
4.10	Conclusions —	123
	Remarks on Chapter 4 —	124
5	Discrete models of the Boltzmann equation —	125
5.1	Introduction to discrete velocity models of the Boltzmann equation —	125
5.2	Construction of normal discrete models —	127
5.3	General discrete kinetic models —	130
5.4	Normal DKMs with given conservation laws —	132
5.5	On classification of normal discrete models of the Boltzmann equation —	134
	Remarks on Chapter 5 —	136
6	Discrete models of the Boltzmann equation and dynamical systems —	137
6.1	General ideas —	137
6.2	Statement of the problem —	138
6.3	DVM as dynamical system —	141
6.4	Linearized equation —	142
6.5	Indices of stationary points —	147
6.6	Applications to half-space problems —	150
6.7	The shock wave problem —	153
6.8	Assumptions and main results —	154
6.9	Transformation of the problem and sketch of the proof —	156
	Remarks on Chapter 6 —	160
7	General Boltzmann-type equations —	161
7.1	Generalization of the Boltzmann equation —	161
7.2	Conservation laws and generalized H -theorem —	164
7.3	Nordheim–Uehling–Uhlenbeck equation and wave kinetic equation —	166
7.4	Discrete kinetic models —	168
7.5	Properties of discrete models —	170
7.6	Some transformations of equations and initial data —	173
7.7	Convergence to equilibrium for discrete models of WKE: Formulation of the main result —	173
7.8	Existence and uniqueness of global nonnegative solutions —	175
7.9	Existence of unique stationary solution —	178
7.10	Properties of the stationary solution —	180
7.11	Proof of convergence to equilibrium —	181

- 7.12 On approximation of Boltzmann-type equations by discrete kinetic models — **184**
- 7.13 Concluding remarks on Chapter 7 — **189**

Bibliography — 191

Index — 199