

Table of Contents

1. Introduction.....	1
2. State of the Art.....	6
2.1 Surgical Robots	6
2.1.1 Bone-Shaping Robots	7
2.1.2 Soft-Tissue Robots	14
2.2 Modularization Theory	15
2.2.1 Dependency-Based Methods	16
2.2.2 Similarity-Based Methods	19
2.2.3 Product Structuring Strategies	21
2.3 Conclusion	23
3. Requirements for the Compatibility with Development Practices of Medical Devices	25
3.1 Target Group	25
3.2 Process Models for the Development of Medical Devices	26
3.3 Product Development in Model-Based Systems Engineering	29
3.4 Process Model for the Systematic Design of Surgical Robots	30
4. Modularization Method	33
4.1 Means of Modularization	34
4.2 Criteria-Based Modularization	36
4.2.1 Generic Module Drivers	36
4.2.2 Context-Specific Module Drivers	39
4.2.3 Expert Feedback	46
4.3 Function-Based Modularization	50
4.3.1 Fundamentals	50
4.3.2 Reference Functions	52
4.4 Decision-Making Scheme	58
4.4.1 Module Indication Matrix	60
4.4.2 List-Based Modularization Scheme	63
5. Integrated Modularization and Risk Estimation.....	66
5.1 Comprehensive Identification of Hazards	68
5.1.1 Point-of-View Framework	70
5.1.2 Use Case Example	75
5.2 Structuration of Hazards	77
5.3 Integration into the Modularization Process	81
6. Computer-Assisted Modularization	84
6.1 Structural Framework	85
6.2 Procedural Approach	89
7. Optimized Intraoperative Interfaces	93
7.1 Design for Assembly	94

7.2	Design for Hygiene	95
7.3	Functional Mock-Up	97
7.4	Supportive Checklist	99
8.	Formative Evaluation	100
8.1	Modularization	100
8.1.1	Results	107
8.1.2	Conclusion	117
8.2	Interface Design Checklist	120
8.2.1	Results	121
8.2.2	Conclusion	123
9.	Discussion and Outlook	125
	Bibliography	133
I	References	133
II	Related Student Theses	150
	List of Figures	151
	List of Tables	154
	Terminology	155
	Appendix	160
	Appendix I Distribution of Expert Feedback by Profession	160
	Appendix II Module Drivers	161
	Appendix III Scenario and Decision Sheets	164