CONTENTS

INTRODUCTION	1					
CHAPTER 1						
GUARANTEED ESTIMATES OF PARAMETER AND STATE VECTORS						
1.1.Guaranteed Estimates of Linear Systems Parameters	5					
1.2.Guaranteed Estimates of Linear Dynamic Systems Parameters	44					
1.3. Guaranteed Estimates of Parameters of Linear Nonstationary						
Discrete Systems	49					
1.4.Simultaneous Construction of Parameter Vectors and State						
Vectors Estimates of Linear Dynamic Systems	58					
1.5.Guaranteed Estimates in Systems Nonlinear in Parameters	67					
CHAPTER 2						
ANALYSIS AND SYNTHESIS OF ADAPTIVE CONTROL SYSTEMS						
2.1.General Characteristic of Adaptive Control Systems	85					
2.2.Synthesis of Adaptive Optimal Stabilizing Systems						
(the Simplest Case)	91					
2.3.Synthesis of Adaptive Optimal Stabilizing Systems						
(the General Case)	112					
2.4.Synthesis of Adaptive Optimal Stabilizing Systems						
for Nonstationary Plants	127					
2.5.Synthesis of Adaptive Optimal Stabilizing Systems						
with Measurement Errors	140					
2.6.Synthesis of Adaptive Control Systems Optimal in Functional	150					
CHAPTER 3						
ANALYSIS AND SYNTHESIS OF ROBUST CONTROL SYSTEMS						
3.1. Analysis and Synthesis of Control Systems under Uncertainty						
Conditions	158					
3.2. Robust Stability of Continuous Dynamic Systems	160					
3.3. Robust Stability of Discrete Dynamic Systems						
3.4. Synthesis of Optimal Robust Linear Control	170 176					
3.5. Synthesis of Optimal Robust Control with Restricted Noise	188					

APPENDIX .	A								
Reduction	οſ	Difference	Equations	of	General	Form	to	Canonical	
Form									196
REFERENCE	S								203
INDEX									208