

Contents

PREFACE	xv
1 INTRODUCTION	1
1.1 Structural Elements	1
1.2 Nonlinearities	4
1.3 Composite Materials	6
1.4 Damping	7
1.5 Dynamic Characteristics of Linear Discrete Systems	9
1.5.1 One-Degree-of-Freedom Systems	9
1.5.2 Multi-Degree-of-Freedom Systems	14
1.6 Dynamic Characteristics of Nonlinear Discrete Systems	22
1.7 Analyses of Linear Continuous Systems	27
1.7.1 Natural Frequencies and Eigenfunctions	30
1.7.2 Discretization Using Eigenfunctions	34
1.7.3 The Ritz Method	35
1.7.4 Finite Element Method	42
1.7.5 Weighted Residual Methods	46
1.7.6 Initial-Value Methods	48
1.8 Analyses of Nonlinear Continuous Systems	53
	vii

1.8.1	<i>Attacking the Continuous System</i>	57
1.8.2	<i>Attacking the Discretized System</i>	60
1.8.3	<i>Time-Averaged Lagrangian</i>	63
2	ELASTICITY	65
2.1	<i>Principles of Dynamics</i>	65
2.1.1	<i>Newton's Second Law and Energy of a Discrete System</i>	67
2.1.2	<i>Principle of Virtual Work</i>	69
2.1.3	<i>Hamilton's Theories</i>	70
2.1.4	<i>Euler-Lagrange Equations</i>	72
2.1.5	<i>Hamilton's Equations</i>	74
2.2	<i>Strain-Displacement Relations</i>	75
2.3	<i>Transformation of Strains and Stresses</i>	82
2.4	<i>Stress-Strain Relations</i>	85
2.4.1	<i>Anisotropic Materials</i>	86
2.4.2	<i>Orthotropic Materials</i>	87
2.4.3	<i>Isotropic Materials</i>	90
2.4.4	<i>Material Stiffness and Compliance Matrices</i>	94
2.4.5	<i>Fiber-Reinforced Lamina</i>	96
2.5	<i>Governing Equations</i>	98
2.5.1	<i>Equilibrium Equations</i>	99
2.5.2	<i>Compatibility Conditions</i>	107
2.5.3	<i>Energy Formulation of Structures</i>	109
3	STRINGS AND CABLES	111
3.1	<i>Modeling of Taut Strings</i>	111
3.1.1	<i>Exact Equations of Motion</i>	113
3.1.2	<i>Approximate Equations of Motion without Poisson's Effect</i>	115
3.1.3	<i>Approximate Equations of Motion with Poisson's Effect</i>	117
3.2	<i>Reduction of String Model to Two Equations</i>	118
3.2.1	<i>Attacking the Three-Equation Model</i>	121
3.2.2	<i>Evaluation of the Two-Equation Model</i>	124
3.2.3	<i>Discretized Model</i>	126
3.3	<i>Nonlinear Response of Strings</i>	129
3.3.1	<i>Frequency-Response Curves</i>	130
3.3.2	<i>Experiments</i>	132

3.4	<i>Modeling of Cables</i>	136
3.4.1	<i>Exact Equations of Motion</i>	139
3.4.2	<i>Static Deflections</i>	141
3.4.3	<i>Approximate Equations of Motion</i>	145
3.5	<i>Reduction of Cable Model to Two Equations</i>	146
3.6	<i>Natural Frequencies and Modes of Cables</i>	148
3.7	<i>Discretization of the Cable Equations</i>	150
3.8	<i>Single-Mode Response with Direct Approach</i>	152
3.8.1	<i>Primary Resonance of an Inplane Mode</i>	153
3.8.2	<i>Primary Resonance of an out-of-Plane Mode</i>	158
3.9	<i>Single-Mode Response with Discretization Approach</i>	161
3.9.1	<i>The Case of an Inplane Mode</i>	162
3.9.2	<i>The Case of an out-of-Plane Mode</i>	167
3.10	<i>Extensional Bars</i>	168
4	<i>BEAMS</i>	171
4.1	<i>Introduction</i>	171
4.1.1	<i>Beam Theories</i>	172
4.1.2	<i>Geometric Nonlinearities</i>	176
4.1.3	<i>Shear Deformations, Rotary Inertias, and Gravity</i>	179
4.1.4	<i>Elastic Couplings</i>	180
4.1.5	<i>External and Internal Resonances</i>	180
4.2	<i>Linear Euler-Bernoulli Beam Theory</i>	183
4.3	<i>Linear Shear-Deformable Beam Theories</i>	186
4.3.1	<i>Third-Order Shear-Deformable Theory</i>	189
4.3.2	<i>Timoshenko's Beam Theory</i>	191
4.3.3	<i>Layerwise Shear-Deformable Theory</i>	192
4.4	<i>Mathematics for Nonlinear Modeling</i>	194
4.4.1	<i>Coordinate Transformations and Curvatures</i>	194
4.4.2	<i>Concept of Orthogonal Virtual Rotations</i>	207
4.4.3	<i>Variation of Curvatures</i>	210
4.4.4	<i>Concept of Local Displacements</i>	211
4.5	<i>Nonlinear 2-D Euler-Bernoulli Beam Theory</i>	215
4.5.1	<i>Shortening Effect</i>	221
4.5.2	<i>Stretching Effect</i>	224
4.5.3	<i>Lagrangian and Eulerian Coordinates</i>	225
4.6	<i>Nonlinear 3-D Euler-Bernoulli Beam Theory</i>	226
4.6.1	<i>Isotropic Beams</i>	234

4.6.2	<i>Composite Beams</i>	235
4.6.3	<i>Taylor-Series Expansions</i>	235
4.6.4	<i>Cantilevered Inextensional Beams</i>	240
4.6.5	<i>Flexural-Flexural Vibration</i>	244
4.7	<i>Nonlinear 3-D Curved Beam Theory Accounting for Warpings</i>	245
4.7.1	<i>Inplane and out-of-Plane Warpings</i>	247
4.7.2	<i>Fully Nonlinear Jaumann Strains</i>	251
4.7.3	<i>Equations of Motion</i>	254
4.7.4	<i>Expansions and Simplified Beam Theories</i>	262
4.7.5	<i>Applications</i>	263
5	<i>DYNAMICS OF BEAMS</i>	267
5.1	<i>Parametrically Excited Cantilever Beams</i>	267
5.1.1	<i>Experiments</i>	267
5.1.2	<i>Principal Parametric Resonance</i>	270
5.1.3	<i>Combination Parametric Resonance</i>	278
5.1.4	<i>Nonplanar Dynamics</i>	284
5.2	<i>Transversely Excited Cantilever Beams</i>	291
5.2.1	<i>Planar Response to a Primary-Resonance Excitation</i>	291
5.2.2	<i>External Subcombination Resonance</i>	298
5.2.3	<i>Nonplanar Dynamics</i>	304
5.3	<i>Clamped-Clamped Buckled Beams</i>	316
5.3.1	<i>Buckling Problem</i>	320
5.3.2	<i>Linear Vibration Problem</i>	321
5.3.3	<i>Nonlinear Local Vibrations - Direct Approach</i>	324
5.3.4	<i>Nonlinear Local Vibrations - Discretization Approach</i>	327
5.3.5	<i>Experiment</i>	331
5.3.6	<i>Global Dynamics</i>	334
5.4	<i>Microbeams</i>	341
5.4.1	<i>Modeling of MEMS Devices</i>	342
5.4.2	<i>Static Deflection</i>	344
5.4.3	<i>Linear Mode Shapes and Frequencies</i>	345
5.4.4	<i>Nonlinear Response to a Primary-Resonance Excitation</i>	346
5.4.5	<i>Reduced-Order Models of MEMS Devices</i>	351

6	SURFACE ANALYSIS	355
6.1	<i>Initial Curvatures</i>	355
6.2	<i>Inplane Strains and Deformed Curvatures</i>	358
6.3	<i>Orthogonal Virtual Rotations</i>	362
6.3.1	<i>Without Inplane Shear Strains</i>	362
6.3.2	<i>With Inplane Shear Strains</i>	363
6.4	<i>Variation of Curvatures</i>	365
6.5	<i>Local Displacements and Jaumann Strains</i>	366
7	PLATES	371
7.1	<i>Introduction</i>	371
7.1.1	<i>Plate Theories</i>	371
7.1.2	<i>Geometric Nonlinearities</i>	375
7.1.3	<i>Plates with Integrated Piezoelectric Materials</i>	376
7.1.4	<i>Linear Vibrations and Buckling of Plates</i>	377
7.1.5	<i>Nonlinear Analyses of Plates</i>	379
7.2	<i>Linear Classical Plate Theory</i>	382
7.2.1	<i>Rectangular Plates</i>	382
7.2.2	<i>Circular Plates</i>	388
7.2.3	<i>General Plates</i>	392
7.3	<i>Linear Shear-Deformable Plate Theories</i>	396
7.3.1	<i>Formulation for Curvilinear Coordinate Systems</i>	396
7.3.2	<i>Rectangular and Circular Plates</i>	401
7.3.3	<i>Different Shear-Warping Functions</i>	402
7.4	<i>Nonlinear Classical Plate Theory</i>	403
7.4.1	<i>Rectangular Plates</i>	403
7.4.2	<i>von Kármán Plate Theory in Polar Coordinates</i>	408
7.4.3	<i>Thermoelastic Equations in Cartesian Coordinates</i>	412
7.4.4	<i>Thermoelastic Equations in Polar Coordinates</i>	415
7.5	<i>Nonlinear Modeling of Rectangular Surfaces</i>	417
7.5.1	<i>Coordinate Transformation, Inplane Strains, and Curvatures</i>	417
7.5.2	<i>Influence of the Inplane Shear Deformation</i>	420
7.5.3	<i>Variation of the Global Strains</i>	425
7.6	<i>General Nonlinear Classical Plate Theory</i>	426
7.7	<i>Nonlinear Shear-Deformable Plate Theory</i>	435
7.7.1	<i>Equations of Motion</i>	436

7.7.2	<i>Nonlinear First-Order Theory</i>	446
7.7.3	<i>Third-Order Theory with von Kármán Nonlinearity</i>	446
7.8	<i>Nonlinear Layerwise Shear-Deformable Plate Theory</i>	446
7.8.1	<i>Warpings Due to External Loads and Actuators</i>	447
7.8.2	<i>Equations of Motion</i>	457
7.8.3	<i>Linear Piezoelectric Plate Theory</i>	465
7.8.4	<i>Actuator-Induced Loads</i>	467
7.8.5	<i>Thermal and Moisture Effects</i>	467
8	DYNAMICS OF PLATES	469
8.1	<i>Linear Vibrations of Rectangular Plates</i>	469
8.1.1	<i>Hinged Edges</i>	470
8.1.2	<i>Two Hinged Opposite Edges</i>	470
8.2	<i>Linear Vibrations of Membranes</i>	474
8.2.1	<i>Circular Membranes</i>	474
8.2.2	<i>Near Circular Membranes</i>	477
8.2.3	<i>Elliptic Membranes</i>	480
8.3	<i>Linear Vibrations of Circular and Annular Plates</i>	481
8.3.1	<i>Circular Plates</i>	482
8.3.2	<i>Near Circular and Elliptic Plates</i>	487
8.3.3	<i>Annular Plates</i>	491
8.4	<i>Nonlinear Vibrations of Circular Plates</i>	498
8.4.1	<i>Axisymmetric Vibrations</i>	503
8.4.2	<i>Asymmetric Vibrations</i>	507
8.5	<i>Nonlinear Vibrations of Rotating Disks</i>	513
8.5.1	<i>Static Problem</i>	516
8.5.2	<i>Natural Frequencies and Mode Shapes</i>	517
8.5.3	<i>Response to a Primary-Resonance Excitation</i>	522
8.6	<i>Nonlinear Vibrations of Near-Square Plates</i>	527
8.7	<i>Micropumps</i>	531
8.7.1	<i>Annular Plates</i>	532
8.7.2	<i>Circular Plates</i>	536
8.8	<i>Thermally Loaded Plates</i>	543
8.8.1	<i>Linear Natural Frequencies and Mode Shapes</i>	548
8.8.2	<i>Combination Parametric Resonance of Two Axisymmetric Modes</i>	549
9	SHELLS	559

9.1	<i>Introduction</i>	559
9.1.1	<i>Shell Theories</i>	560
9.1.2	<i>Nonlinear Vibrations of Shells</i>	563
9.2	<i>Linear Classical Shell Theory</i>	566
9.2.1	<i>Different Shell Geometries</i>	566
9.2.2	<i>Doubly-Curved Shell Theory</i>	571
9.2.3	<i>Circular Cylindrical Shell Theory</i>	576
9.3	<i>Linear Shear-Deformable Shell Theories</i>	577
9.3.1	<i>Formulation for General Shells</i>	577
9.3.2	<i>Equations of Motion for Different Shells</i>	581
9.3.3	<i>Shear-Warping Functions</i>	581
9.4	<i>Nonlinear Classical Theory for Doubly-Curved Shells</i>	582
9.5	<i>Nonlinear Shear-Deformable Theories for Circular Cylindrical Shells</i>	588
9.5.1	<i>Equations of Motion</i>	589
9.5.2	<i>Simplified Shell Theories</i>	603
9.5.3	<i>Stiffness Matrices</i>	608
9.5.4	<i>Classical Linear Theories of Circular Cylindrical Shells</i>	611
9.6	<i>Nonlinear Layerwise Shear-Deformable Shell Theory</i>	615
9.6.1	<i>Strains and Shear-Warping Functions</i>	615
9.6.2	<i>Inertia Terms</i>	620
9.6.3	<i>Structural Terms</i>	622
9.6.4	<i>Equations of Motion</i>	625
9.6.5	<i>Shear-Warping Functions</i>	627
9.7	<i>Nonlinear Dynamics of Infinitely Long Circular Cylindrical Shells</i>	630
9.7.1	<i>Governing Equations</i>	631
9.7.2	<i>Natural Frequencies and Mode Shapes</i>	635
9.7.3	<i>Primary Resonance of the Breathing Mode</i>	638
9.8	<i>Nonlinear Dynamics of Axisymmetric Motion of Closed Spherical Shells</i>	641
9.8.1	<i>Equations of Motion</i>	641
9.8.2	<i>Natural Frequencies and Mode Shapes</i>	646
9.8.3	<i>Two-to-One Internal Resonance</i>	649
	<i>BIBLIOGRAPHY</i>	654
	<i>SUBJECT INDEX</i>	732