

CONTENTS

I	HISTORICAL ORIGINS OF THE INVISCID MODEL	1
1.1	From Antiquity to the Renaissance	2
1.2	The Enlightenment: the Age of Reason	4
1.2.1	Leonhard Euler	5
1.3	The 19th Century: Mathematical Fluid Mechanics	8
1.3.1	Vortex Discontinuities and Resistance	9
1.3.2	Shock Waves	11
1.4	The 20th Century: The Computational Era	13
1.4.1	Early Methods	13
1.4.2	Methods to Solve the Euler Equations: 1950-1970 .	14
1.4.3	Methods to Solve the Euler Equations: 1970-1990 .	17
1.5	Brief Overview of Field	18
1.5.1	Secondary Reference Sources	18
1.5.2	Three Categories of Methods	20
1.6	Outline of the Remaining Chapters	21
1.7	References	22
II	THE EULER EQUATIONS	27
2.1	The Classical Euler Equations in Gas Dynamics	27
2.2	Basic Results of the Non-Conservative Equations	28
2.2.1	Isentropic Flow	28
2.2.2	Homentropic Flow	29
2.3	Basic Results of the Conservative Equations	30
2.3.1	Isenthalpic Flow	30
2.3.2	Shock Flow	31
2.3.3	Speed of Sound	36
2.3.4	Eigenvalues of Pressure Waves	36
2.3.5	Homogeneous Property of the Euler Equations	37
2.4	Coordinate Transformations	38
2.5	Stokes' Integral	42
2.6	Physical Boundary Conditions	43
2.7	Other Forms of the Euler Equations	43
2.8	References	45

CONTENTS (continued)

III	FUNDAMENTALS OF DISCRETE SOLUTION METHODS	47
3.1	Hyperbolic Equations and Waves	47
3.2	Characteristics	49
3.3	Wavefronts Bounding a Constant State	53
3.4	Riemann Invariants	54
3.5	Well-Posed and Unique Solutions	59
3.6	Initial Boundary-Value Problems	61
3.7	Weak Solutions and Shocks	64
3.8	Discrete Solution Methods	70
3.9	Classical Finite-Difference Approximations to	72
	Derivatives	
3.10	Computational Grid and Accuracy	72
3.11	Local Truncation Error	73
3.12	Consistency	75
3.13	Convergence and Stability	75
3.14	Notion of Convergence	76
3.15	Notion of Stability	77
	3.15.1 A Bound for the Spectral Radius	77
3.16	Von Neumann Method	78
3.17	Matrix Method	79
3.18	The Energy Method	80
3.19	Schemes for Non-Linear Equations	83
3.20	References	86
IV	THE FINITE VOLUME CONCEPT	89
4.1	Coordinate Transformations	89
	4.1.1 The Differential Approach	89
4.2	The Finite-Volume Approach	90
	4.2.1 Continuum Equations	90
	4.2.2 Coordinate Geometry	91
	4.2.3 Spatial Finite-Volume Discretization	94
	4.2.4 Flux Evaluation	95
	4.2.5 Stability and Accuracy at Mesh Singularities ...	96
4.3	Relationship to Finite Differences	96
4.4	Numerical Conservation	97
	4.4.1 Uniform Free Stream	98
4.5	Cell Vertex Methods	98

CONTENTS (continued)

4.6	Boundary Conditions for the Continuous Problem	98
4.6.1	Coordinate Cuts	99
4.6.2	Solid Walls	100
4.6.3	Zero-Flux Transport	100
4.6.4	Inflow/Outflow Boundary	101
4.7	Discretization of the Flow Domain	104
4.7.1	Resolution of Scales	106
4.7.2	Topology of Grid-Point Patterns	107
4.8	Finite-Volume Truncation Error	108
4.9	Multi-Block Meshes	111
4.10	Boundary Conditions for the Discrete Problem	115
4.10.1	Accuracy and Stability	116
4.10.2	Empirical Rule for Boundary-Condition Accuracy	116
4.10.3	Farfield Boundary Conditions	117
4.11	References	120
V	CENTERED DIFFERENCING	123
5.1	Flux-Averaged Methods	124
5.2	Local Fourier Stability	126
5.3	Local Time-Step Scaling	130
5.4	Artificial-Viscosity Model	131
5.4.1	Non-Linear Artificial Viscosity	132
5.4.2	Linear Artificial Viscosity	133
5.4.3	Boundary Conditions	133
5.5	Time Integration and Convergence to Steady State	136
5.5.1	Steady State Operator	139
5.5.2	Eigenspectrum of Centered Schemes	140
5.6	References	142
VI	PRINCIPLES OF UPWINDING	145
6.1	Initial Considerations	145
6.2	Foundation of Upwinding	149
6.3	A Local Solution to the Model Equation	152
6.4	Conservative Upwinding	153
6.5	Accuracy of Three-Point Schemes	155
6.6	Stability Considerations for Three-Point Schemes	156
6.7	The Finite-Volume Cell-Face Concept	156
6.8	The Riemann Problem at a Finite-Volume Cell Face	159
6.9	The Characteristic Derivative	160

CONTENTS (continued)

6.10	The Scalar Invariant	162
6.11	Characteristic Condition	163
6.12	Eigenvalues and Invariants	164
6.13	A Simple Linear Riemann Solver	166
6.14	A Near Exact Riemann Solver	169
6.15	The Isentropic Riemann Solver	170
6.16	An Osher-Type Riemann Solver	171
6.17	A Linear Riemann Solver Using Primitive Variables	174
6.18	The Exact Non-Conservative Riemann Solver	177
6.19	An Alternative Osher-Type Approximate Riemann Solver	177
6.20	Asymmetric Osher-Type Approximate Riemann Solvers	179
6.21	A Linear Newton-Type Riemann Solver	180
6.22	A Quadratic Newton-Type Riemann Solver	181
6.23	A Linear Conservative Riemann Solver	182
6.24	The Exact Conservative Riemann Solver	183
6.25	Roe's Average	183
6.26	Riemann Solvers Based on Fluxes: The Steger-Warming Fluxes	186
6.27	Generalized Steger-Warming Fluxes	187
6.28	Einfeldt-Type Fluxes	188
6.29	Van Leer-Type Fluxes	190
6.30	1D-Mass Flux of van Leer Type	192
6.31	1D-Momentum Flux of van Leer Type	193
6.32	1D-Energy Flux of van Leer Type	194
6.33	3D-Mass Flux	195
6.34	3D-Momentum Fluxes	196
6.35	3D-Energy Flux	197
6.36	The Use of the Conservative Riemann Solver for Splitting Flux Differences	198
6.37	The Use of the Conservative Riemann Solver for Splitting Flux Differences by Projection	200
6.38	Evaluation of Eigenvalues by Projection	203
6.39	Non-Oscillating Interpolation: Introduction	205
6.40	Five-Point Schemes	206
6.41	First-Order Upwind Scheme	207

CONTENTS (continued)

6.42	Second-Order Upwind Scheme	208
6.43	Third-Order Biased Upwind Scheme	208
6.44	Fourth-Order Centered Scheme	209
6.45	The von Neumann Stability Test for Upwind Schemes	210
6.46	Criticism on the von Neumann Stability Test for Upwind Schemes	216
6.47	Extremum Principles for Upwind Schemes	216
6.48	Foundation of Flux Limiting	219
6.49	Flux Limiting by Sensing Functions	220
6.50	Flux Limiting by Biased Differences	222
6.51	Flux Limiting with Minimum Dispersion	223
6.52	Limiters	225
6.53	Seven-Point Schemes	228
6.54	Truth Functions	229
6.55	Non-oscillating Interpolation and Riemann Solvers ...	230
6.56	Riemann Solvers and Strong Shocks	232
6.57	Riemann Solvers and Boundary Conditions	235
6.58	Other Updates	237
6.59	Lax-Wendroff (L-W) Type Updates	238
6.60	Implicit Updates	242
6.61	Implicit Formulation	243
6.62	The Split Matrix	245
6.63	The Homogeneous Implicit Solution	246
6.64	Matrix Conditioning	247
6.65	References	252
VII	CONVERGENCE TO STEADY STATE	255
7.1	Introduction	255
7.2	Mathematical Understanding of Convergence	256
	7.2.1 The Continuous Problem	256
	7.2.2 Linear Semi-Discrete Problem	260
	7.2.3 Linearized Euler Equations	263
	7.2.4 Effect of Discrete Space Operator	266
7.3	Multi-Grid Scheme	267
7.4	Enthalpy Damping	270
7.5	Residual Averaging	271
7.6	Mesh Sequencing	275
7.7	References	276

CONTENTS (continued)

VIII	A NOTE ON THE USE OF SUPERCOMPUTERS	277
8.1	Supercomputers as Driver of Computational Fluid Dynamics	277
8.2	Future Developments in Supercomputing: Parallel Processing	278
8.3	References	279
IX	COUPLING OF EULER SOLUTIONS TO VISCOUS MODELS	281
9.1	Diffusive Transport Effects in Fluid Flows	281
9.2	Treatment of Weak Interaction Flow Problems	285
9.3	Treatment of Strong Interaction Flow Problems	287
9.4	References	289
X	MODELLING OF VORTEX FLOWS: VORTICITY IN EULER SOLUTIONS	293
10.1	Boundary Layers, Wakes and Vortices in their Inviscid Limit	293
10.2	The Lifting Wing as Inviscid Computation Problem	300
10.3	The Structure of the Wake of a Lifting Wing	303
10.4	Vorticity Creation and Entropy Rise in Euler Solutions for Lifting Wings	309
10.5	The State of the Art: a Critical Evaluation	316
10.6	A Note on the Solution of the Navier-Stokes Equations	320
10.7	References	320
XI	METHODS IN PRACTICAL APPLICATIONS	323
11.1	Near-Incompressible Flow	323
11.1.1	Transverse Circular Cylinder	323
11.1.2	Some Numerical Experiments on Transverse Cylinders	324
11.1.3	Airfoil with Lift	329
11.1.4	Vortex Flow Over Sharp-Edged Delta Wing	332
11.1.5	Flow Through a Francis Water Turbine	342
11.1.6	Flow Past an Automobile	346
11.2	Subsonic/Transonic Flow	348
11.2.1	Comparison of Different Riemann Solvers	348
11.2.2	Flow Around Airfoils	354
11.2.3	Vortex Flow Over Sharp-Edged Delta Wings	358
11.2.4	Vortex Flow Over Round-Edged Delta Wings	367
11.2.5	Analysis of Flow Around a Project Wing	376
11.2.6	Flow Through Ducts	383

CONTENTS (continued)

11.3	Supersonic/Hypersonic Flow	385
11.3.1	Leeside Flow Using Centered Scheme	385
11.3.2	Computation of Leeside Flow Using an Upwind Scheme	387
11.3.3	Supersonic Flow Around Delta Wings	389
11.4	Flow Past Complex Configuratons	394
11.4.1	Generic Fighter Configuration at Transonic and Supersonic Speed	394
11.4.2	Flow past Hypersonic Generic Aircraft	397
11.4.3	Equilibrium Real-Gas Solution for a Reentry Configuration	398
11.5	Coupling with Viscous Models	401
11.6	A Note on Unsteady Applications	408
11.7	References	408
XII	FUTURE PROSPECTS	417
12.1	General Considerations	417
12.2	Beyond Dimensional Splitting	419
12.3	Finite Element Formulations	421
12.4	Geometric Complexity	422
12.5	Interdisciplinary Problems	423
12.6	References	425
XIII	LIST OF SYMBOLS	429
XIV	INDEX OF AUTHORS	441
XV	SUBJECT INDEX	445