

Table of Contents

AMPLE Workshop

Methods

Leveraging Multiple Mechanisms for Information Propagation (Extended Abstract)	1
<i>Andrew W. Wicker and Jon Doyle</i>	
A Case Study in Model Selection for Policy Engineering: Simulating Maritime Customs	3
<i>Hassan Harb, F. Jordan Srouf, and Neil Yorke-Smith</i>	
Towards Qualitative Reasoning for Policy Decision Support in Demonstrations	19
<i>Natalie Fridman, Gal A. Kaminka, and Avishay Zilka</i>	
The Role of MAS as a Decision Support Tool in a Water-Rights Market	35
<i>Vicente Botti, Antonio Garrido, Adriana Giret, and Pablo Noriega</i>	

Culture

Understanding Compliance Differences between Legal and Social Norms: The Case of Smoking Ban	50
<i>Francien Dechesne, Virginia Dignum, and Yao-Hua Tan</i>	
Modelling Culture in Multi-agent Organizations	65
<i>Alexis Morris, William Ross, and Mihaela Ulieru</i>	
Substantiating Agent-Based Quality Goals for Understanding Socio-Technical Systems	80
<i>Sonja Pedell, Tim Miller, Leon Sterling, Frank Vetere, and Steve Howard</i>	

Policy Formulation

An Analysis and Design Framework for Agent-Based Social Simulation	96
<i>Amineh Ghorbani, Virginia Dignum, and Gerard Dijkema</i>	
The Benefits of Agent-Based Motivation Models in Policy Formulation and Implementation	113
<i>Sonja Pedell and Leon Sterling</i>	

AOSE Workshop

AgentStore — A Pragmatic Approach to Agent Reuse	128
<i>Axel Hessler, Benjamin Hirsch, Tobias Küster, and Sahin Albayrak</i>	
Dynamically Adapting BDI Agents Based on High-Level User Specifications	139
<i>Ingrid Nunes, Michael Luck, Simone Diniz Junqueira Barbosa, Simon Miles, and Carlos J.P. de Lucena</i>	
Engineering Coordination: Selection of Coordination Mechanisms	164
<i>René Schumann</i>	
Augmenting Android with AOSE Principles for Enhanced Functionality Reuse in Mobile Applications	187
<i>Christopher Frantz, Mariusz Nowostawski, and Martin K. Purvis</i>	

ARMS Workshop

Human-Robot Interaction

The iCat as a Natural Interaction Partner: Playing Go Fish with a Robot	212
<i>Koen Hindriks, Mark A. Neerincx, and Mirek Vink</i>	
Designing the HRTeam Framework: Lessons Learned from a Rough-and-Ready Human/Multi-Robot Team	232
<i>Elizabeth Sklar, A. Tuna Ozgelen, J. Pablo Munoz, Joel Gonzalez, Mark Manashirov, Susan L. Epstein, and Simon Parsons</i>	
Flood Disaster Mitigation: A Real-World Challenge Problem for Multi-agent Unmanned Surface Vehicles	252
<i>Paul Scerri, Balajee Kannan, Pras Velagapudi, Kate Macarthur, Peter Stone, Matt Taylor, John Dolan, Alessandro Farinelli, Archie Chapman, Bernadine Dias, and George Kantor</i>	

Robot Perception

AnySURF: Flexible Local Features Computation	270
<i>Eran Sadeh-Or and Gal A. Kaminka</i>	
Robot Navigation with Weak Sensors	272
<i>Noa Agmon, Yehuda Elmaliah, Yaron Mor, and Oren Slor</i>	

Robot Exploration

Individual Localization and Tracking in Multi-robot Settings with Dynamic Landmarks (Extended Abstract)	277
<i>Anousha Mesbah and Prashant Doshi</i>	
Fast Frontier Detection for Robot Exploration	281
<i>Matan Keidar, Eran Sadeh-Or, and Gal A. Kaminka</i>	

Robots in Motion

Lazy Auctions for Multi-robot Collision Avoidance and Motion Control under Uncertainty	295
<i>Jan-P. Calliess, Daniel Lyons, and Uwe D. Hanebeck</i>	
Multi-robot Path Planning with the Spatio-Temporal A* Algorithm and Its Variants	313
<i>Wenjie Wang and Wooi-Boon Goh</i>	

Multi-robot Teamwork

Adaptive Multi-robot Team Reconfiguration Using a Policy-Reuse Reinforcement Learning Approach	330
<i>Prithviraj Dasgupta, Ke Cheng, and Bikramjit Banerjee</i>	
Bounded Optimal Constrained Coordination with Delay Penalties and Location Choice (Extended Abstract)	346
<i>G. Ayorkor Korsah, Anthony Stentz, and M. Bernardine Dias</i>	

DOCM³AS Workshop

Modeling Human Behavior Selection under Environmental Subsidy Policy by Multi-agent Simulation	350
<i>Tomoko Imoto, Shin'ya Nakano, and Tomoyuki Higuchi</i>	
TaxiSim: A Multiagent Simulation Platform for Evaluating Taxi Fleet Operations	359
<i>Shih-Fen Cheng and Thi Duong Nguyen</i>	
Parallel Agent-Based Simulator for Influenza Pandemic	361
<i>Masaya M. Saito, Seiya Imoto, Rui Yamaguchi, Satoru Miyano, and Tomoyuki Higuchi</i>	
A Hybrid Macro-Micro Pedestrians Evacuation Model to Speed Up Simulation in Road Networks	371
<i>Nguyen Thi Ngoc Anh, Zucker Jean Daniel, Nguyen Huu Du, Alexis Drogoul, and Vo Duc An</i>	

A Unified Agent-Based Model to Analyze Organizational Deviation and Kaizen Activities	384
<i>Tomomi Kobayashi, Satoshi Takahashi, Masaaki Kunigami, Atsushi Yoshikawa, and Takao Terano</i>	

ITMAS Workshop

Agent-Based Simulation Platform Evaluation in the Context of Human Behavior Modeling	396
<i>Michal Laclavík, Štefan Dlugolinský, Martin Šeleng, Marcel Kvassay, Bernhard Schneider, Holger Bracker, Michał Wrzeszcz, Jacek Kitowski, and Ladislav Hluchý</i>	
An Agent Infrastructure for Privacy-Enhancing Agent-Based E-commerce Applications	411
<i>Jose M. Such, Agustín Espinosa, and Ana Garcia-Fornes</i>	
Auto-Adaptation of Open MAS through On-Line Modifications of the Environment	426
<i>Roberto Centeno and Holger Billhardt</i>	
Combining Semantic Web and Logic Programming for Agent Reasoning	428
<i>Murat Şensoy, Wamberto W. Vasconcelos, and Timothy J. Norman</i>	
Cost-Aware Reorganization Service for Multiagent Systems	442
<i>Juan M. Alberola, Vicente Julian, and Ana Garcia-Fornes</i>	
A Distributed Architecture for Enforcing Norms in Open MAS	457
<i>Natalia Criado, Estefania Argente, Pablo Noriega, and Vicent Botti</i>	
Evolving Semantics for Agent-Based Collaborative Search	472
<i>Murat Şensoy</i>	
Micro-agents on Android: Interfacing Agents with Mobile Applications	488
<i>Christopher Frantz, Mariusz Nowostawski, and Martin K. Purvis</i>	
Introduction to Prognostic Normative Reasoning	503
<i>Jean Oh, Felipe Meneguzzi, Katia Sycara, and Timothy J. Norman</i>	
Author Index	505