

Contents

1	Introduction	1
1.1	Motivation	1
1.2	Outline and Contribution	4
2	Concepts of Display-Camera Communication	7
2.1	Non-Hidden DCC	9
2.2	Hidden DCC	11
2.3	DaVid System	11
2.3.1	Display Area Detection	13
2.3.2	Frame Recovery	14
2.3.3	Sampling Point Reconstruction	16
2.4	Conclusion	17
3	Noise and Interference	19
3.1	Receiver Camera Noise	20
3.1.1	Photon Noise	21
3.1.2	Dark Noise	22
3.1.3	Quantization Noise	23
3.2	Environmental Noise Sources	23
3.3	Interference	24
3.3.1	Temporal Interference	24
3.3.2	Spatial Interference	26
3.3.3	Color Crosstalk	28
3.4	Conclusion	30

4	Channel Model and Capacity for the Pixel-Matched Channel	33
4.1	Camera Signal and Noise Model	34
4.1.1	Camera Signal Model	34
4.1.2	Camera Noise Model	38
4.2	Signal and Noise Model for the Differential Display-Camera Channel	39
4.2.1	Differential DCC Signal Model	39
4.2.2	Differential DCC Noise Model	42
4.2.3	Description as a Discrete Time Channel	44
4.3	Capacity of the Differential Channel	48
4.3.1	Channel Capacity using Gaussian Distributed Channel Inputs	48
4.3.2	Channel Capacity using a Binary Modulation	51
4.4	Impact of Color Crosstalk	53
4.4.1	Compensation of Color Crosstalk	56
4.4.2	Modulation in the YUV color space	58
4.5	Conclusion	59
5	Channel Model and Capacity under Spatial Interference	61
5.1	Preliminary Considerations	62
5.1.1	Display and Camera Alignment	62
5.1.2	Display Pixel Aperture	63
5.1.3	Receiver Camera	64
5.1.4	Spatial Grouping	66
5.2	Spatial Symbol Interference	70
5.2.1	Impulse Shape at the Receiver	70
5.2.1.1	Modifications for a 1-chip Camera with Bayer Pattern	78
5.2.2	Receiver Filter	80
5.2.3	Spatial Crosstalk	85
5.3	SINR and Channel Capacity	88
5.3.1	Gaussian Distributed Channel Inputs	89
5.3.2	Binary Channel Inputs	90

5.3.3	Average Channel Capacity	92
5.4	Impact of Color Crosstalk	95
5.4.1	Color Crosstalk in a 3-Chip Camera	95
5.4.2	Color Crosstalk in a 1-Chip Camera	97
5.5	Recursive Interference Cancellation	99
5.6	Conclusion	109
6	Evaluation	111
6.1	Measurements of the Channel	111
6.1.1	Dark Signal Compensation	112
6.1.2	Measurement of the Display-Camera Specific Parameters	112
6.2	Evaluation of the Pixel-Matched Channel	116
6.2.1	Channel Capacity without Color Crosstalk	117
6.2.2	Channel Capacity with Color Crosstalk	123
6.3	Evaluation of the Channel with Spatial Interference	126
6.3.1	Channel Capacity for Different Projected Block Sizes .	127
6.3.2	Channel Capacity per Pixel Area	130
6.3.3	Influence of Image Blur	132
6.4	Evaluation of the Recursive Interference Cancellation	133
6.5	Comparison with Binary Channel Inputs	137
6.6	Comparison with Results of the DaViD Project	139
6.7	Conclusion	144
7	Conclusion and Outlook	147
7.1	Summary	147
7.2	Discussion and Outlook	149
	Abbreviations	151
	Symbols	153
	Glossary	163
	List of Figures	165

List of Tables	176
A Appendix	179
A.1 Color Space Transformations	179
A.2 Probability Density of the Interference for the Binary Channel .	179
A.3 Additional Plots	182
Bibliography	197
Publications by the Author	203
Student Works Supervised by the Author	205
Curriculum Vitae	207